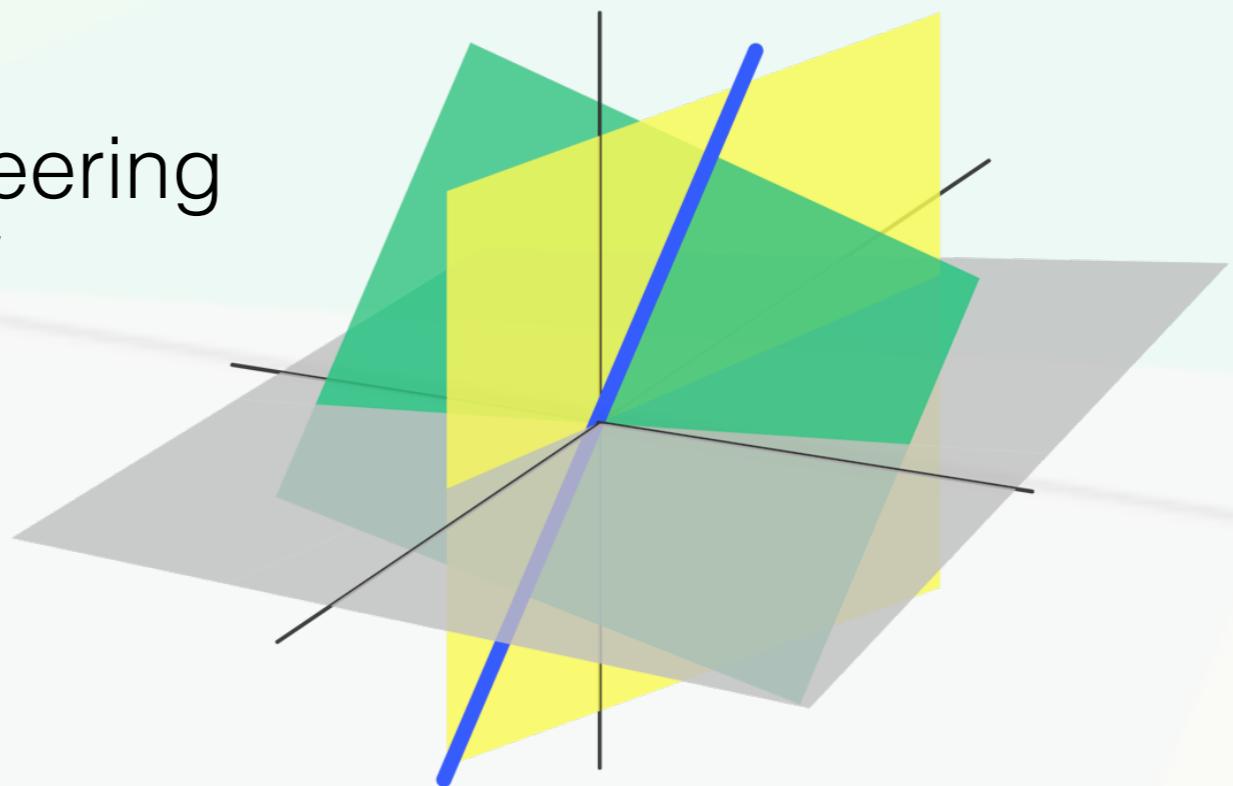


Finding **low-dimensional** structure in **large-scale** neural datasets

Eva Dyer

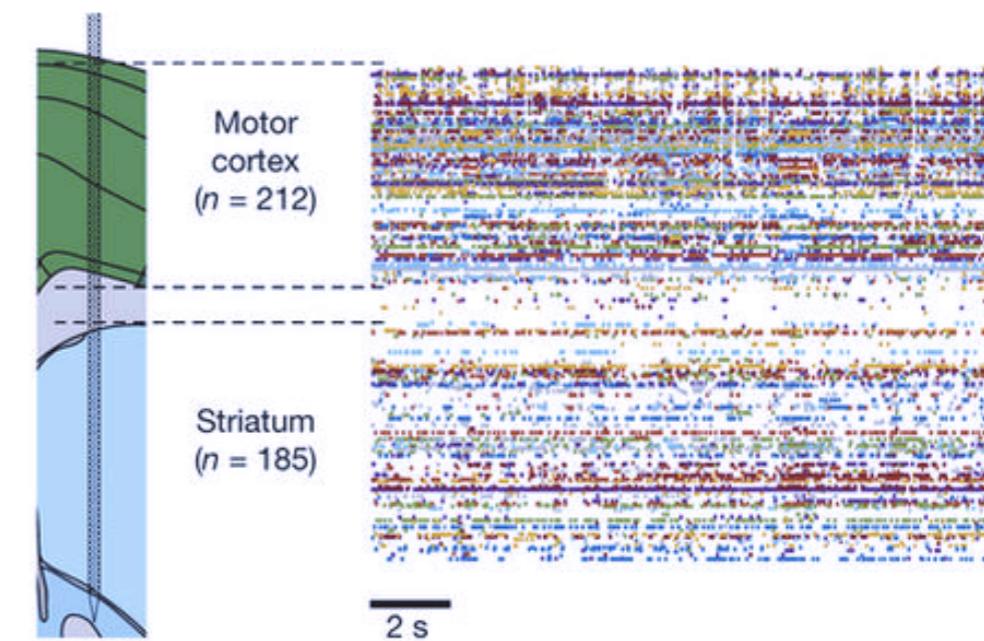
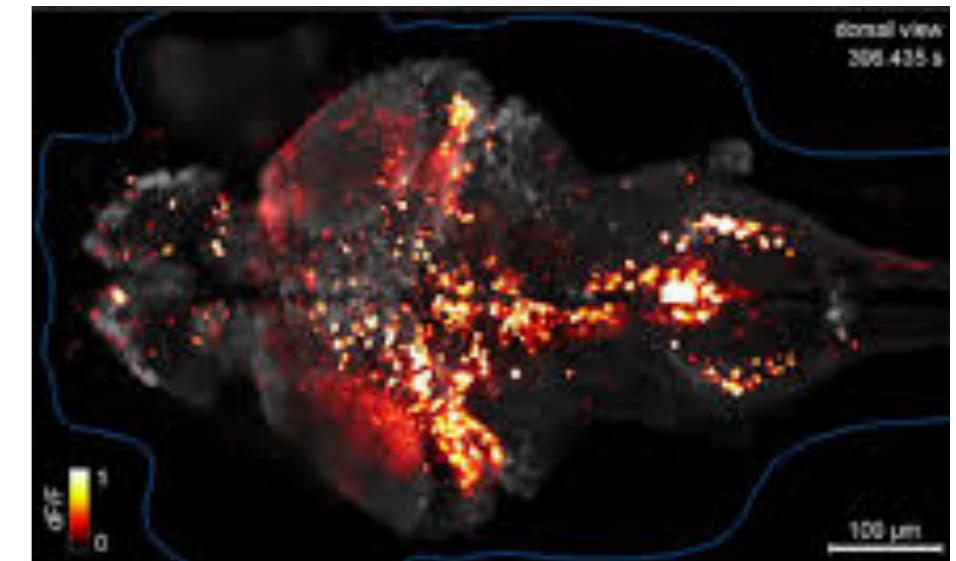
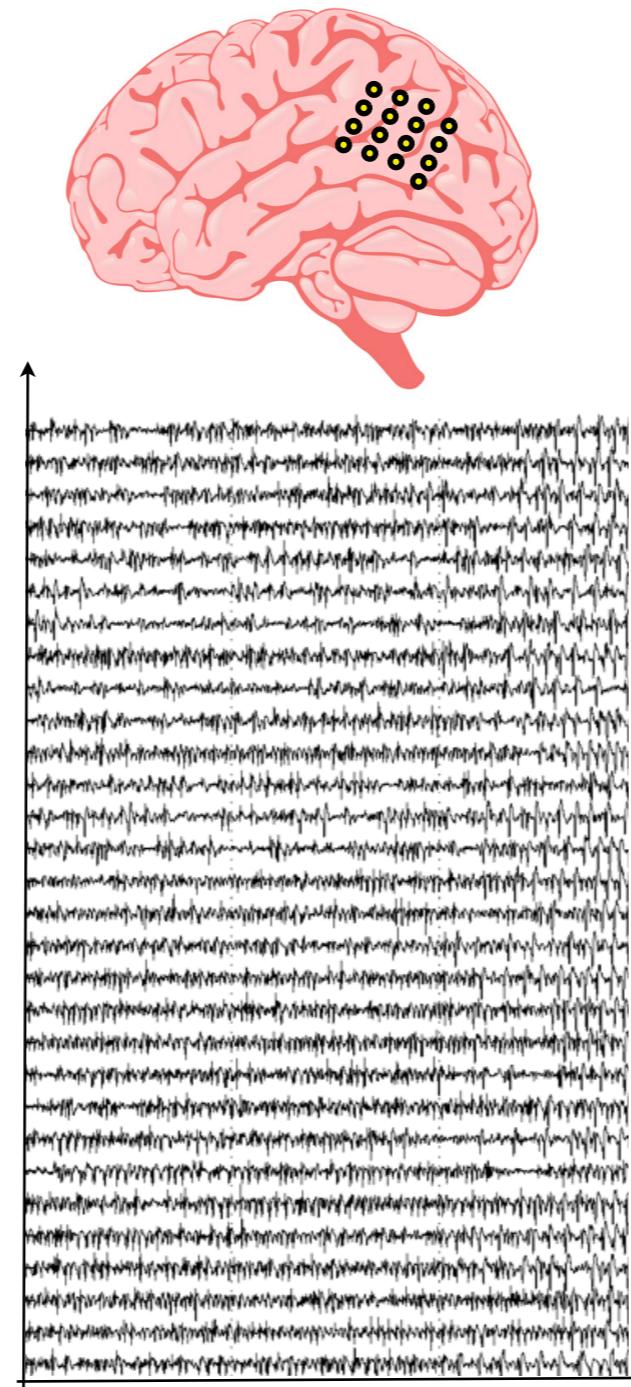
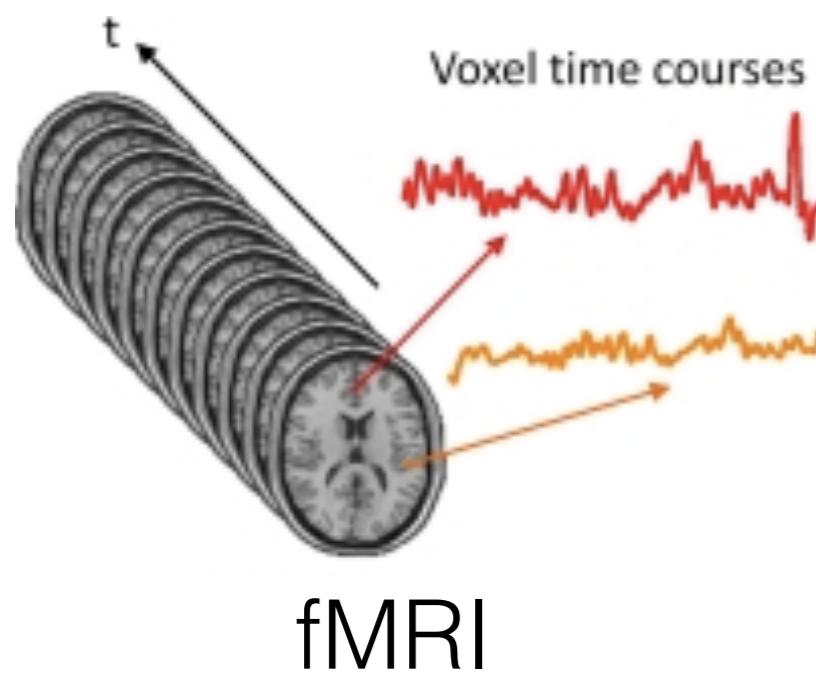
Department of Biomedical Engineering
Georgia Institute of Technology //
Emory University



EMORY
UNIVERSITY

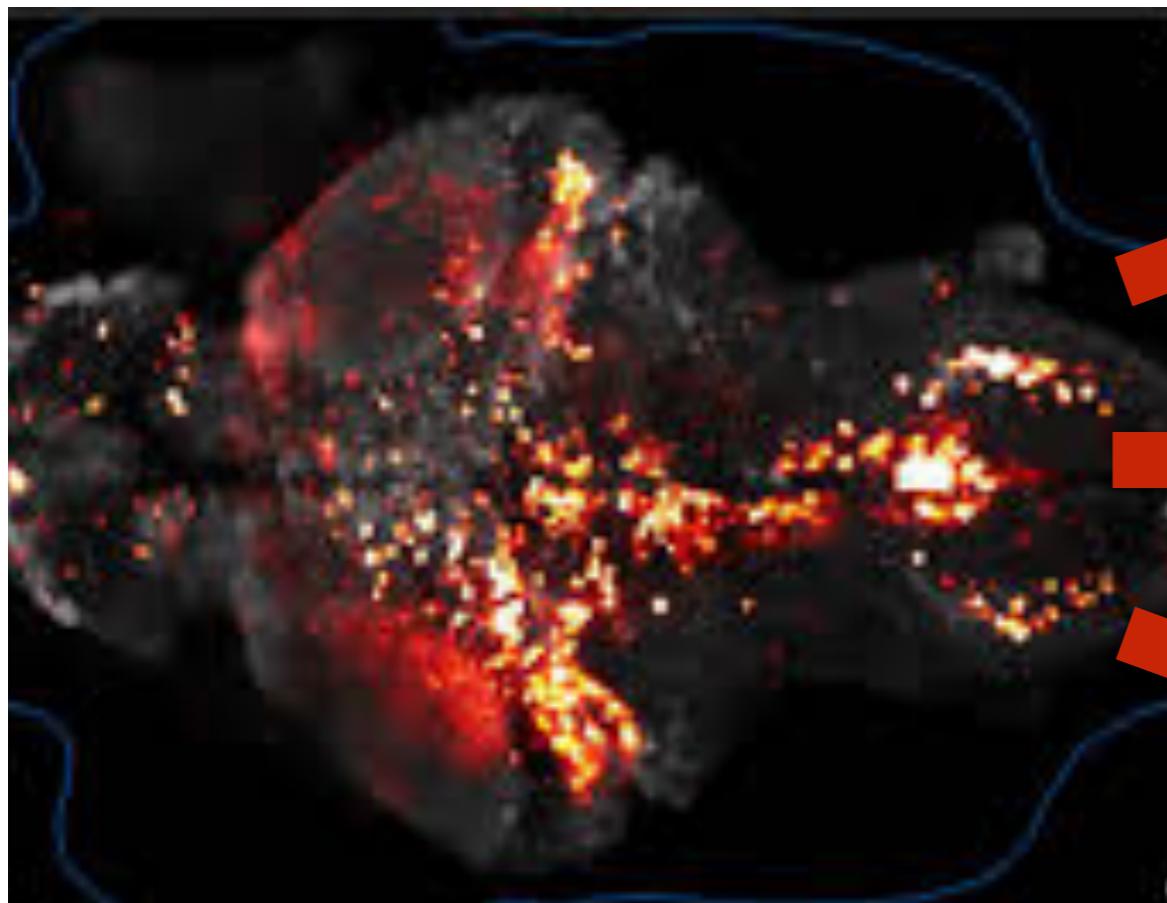
NeuroHackademy - Aug 3 2018

neural data deluge



DTI

why reduce dimensionality?

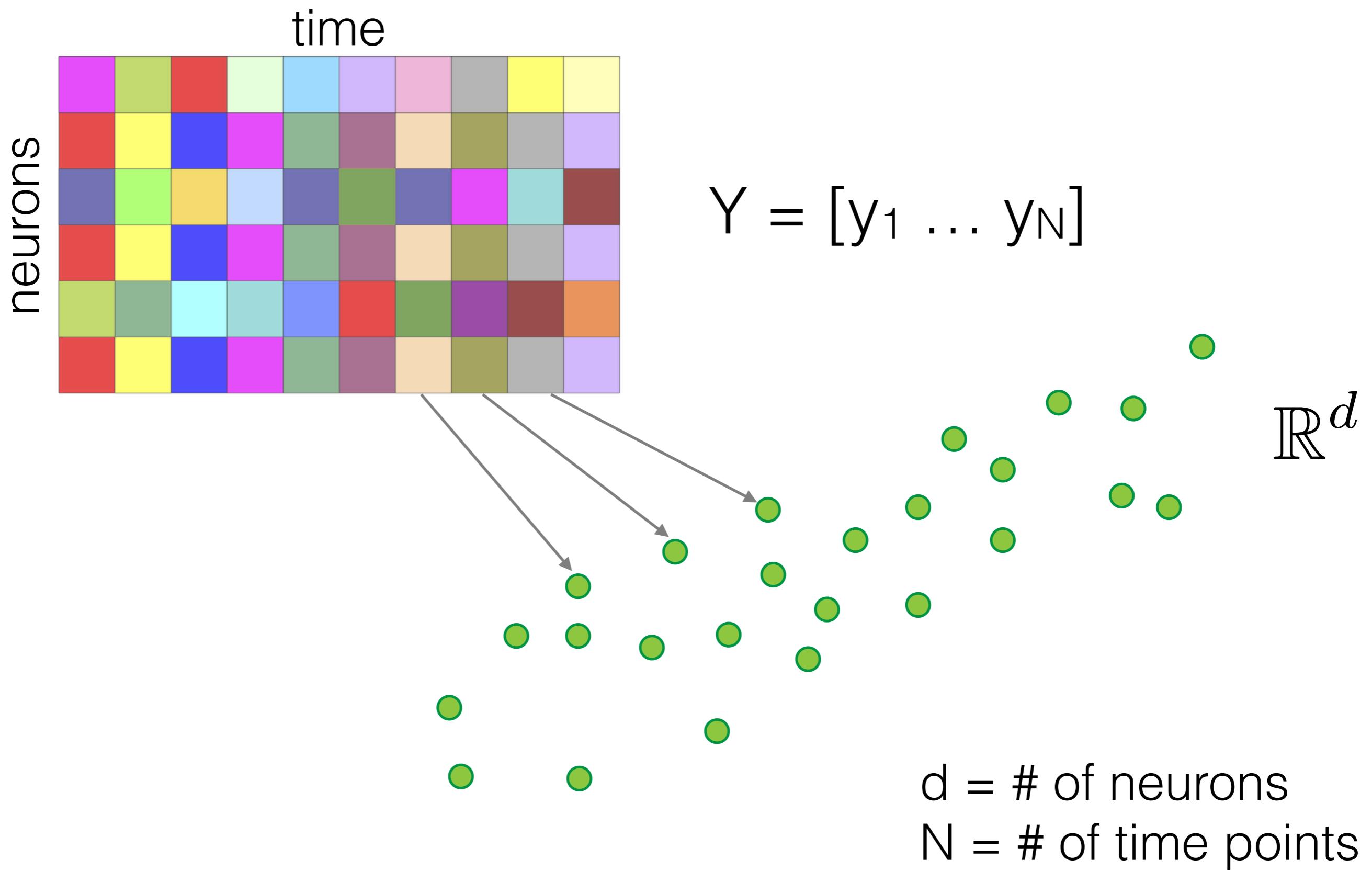


compression

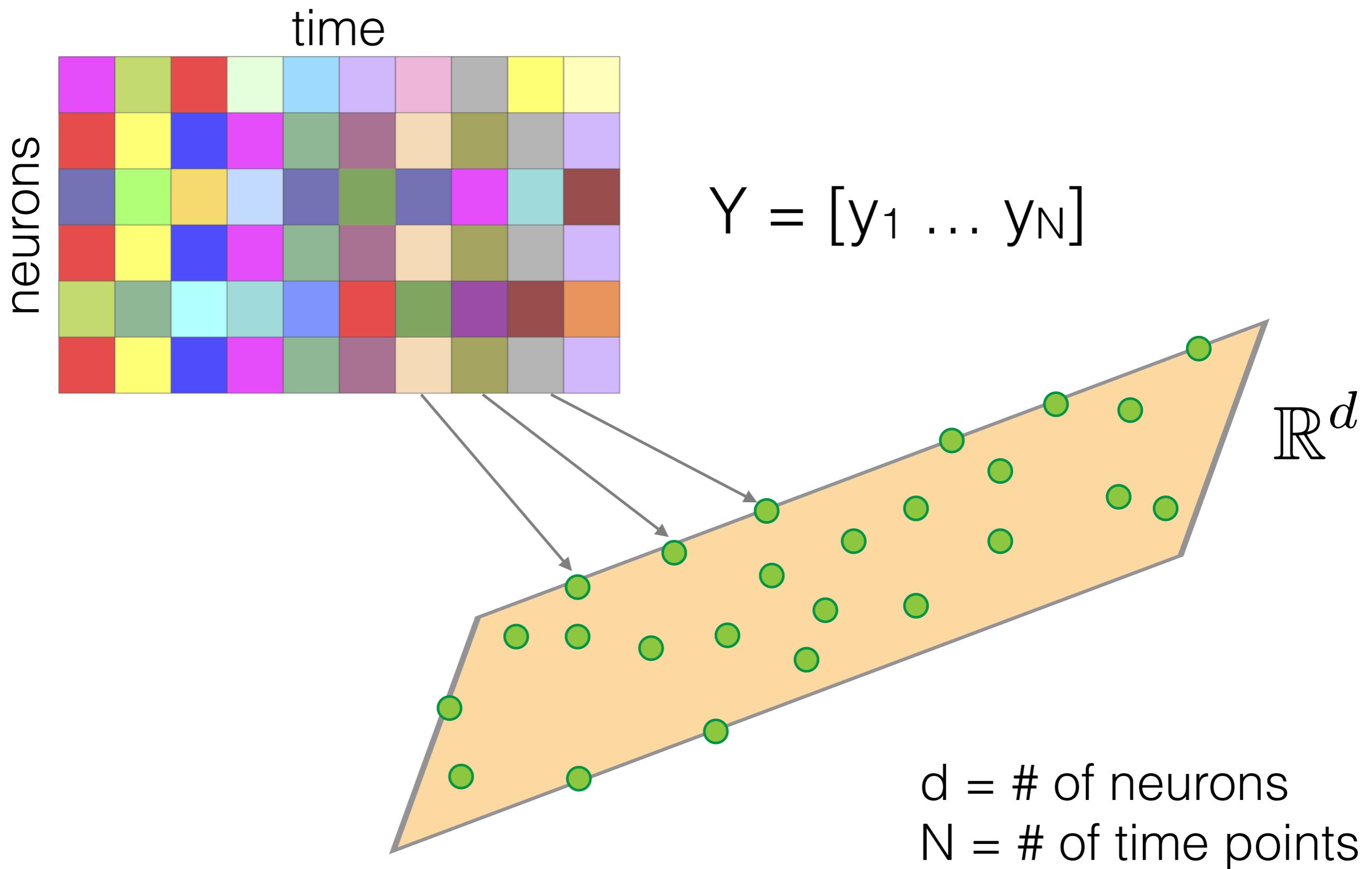
denoising

interpret complex data

low-dimensional models

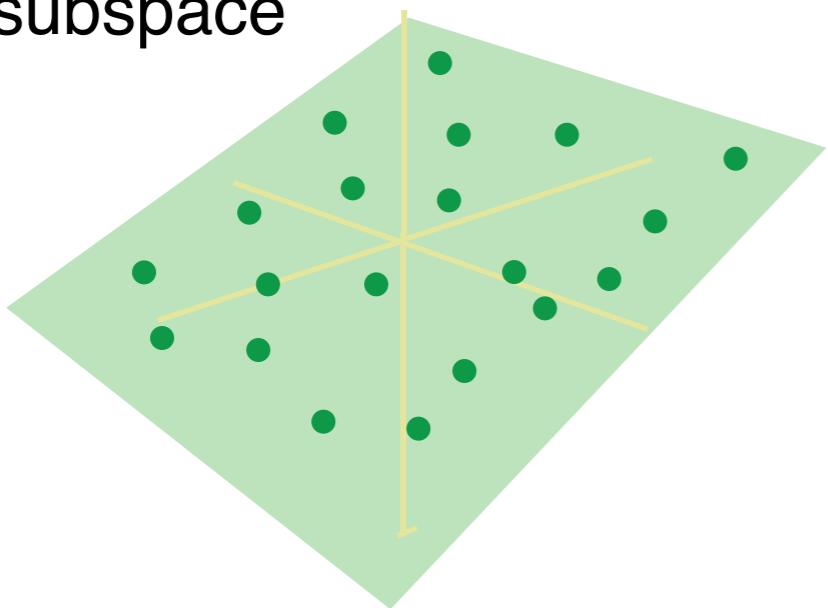


low-dimensional models



low rank model

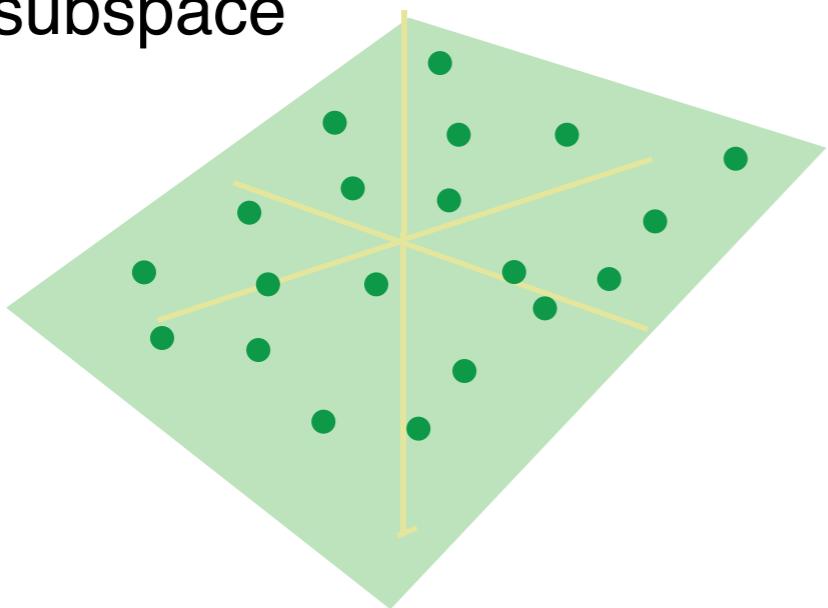
linear subspace
PCA



$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$

low rank model

linear subspace
PCA



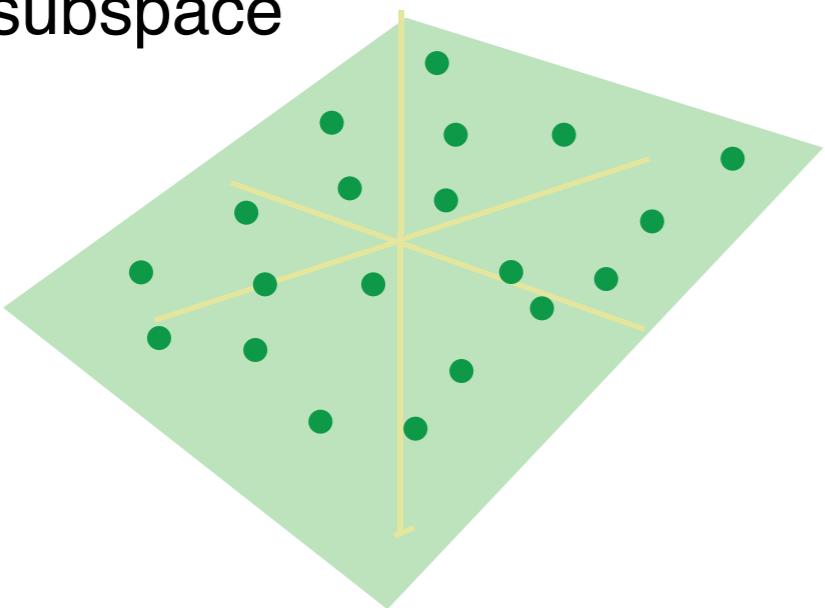
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



data matrix

low rank model

linear subspace
PCA



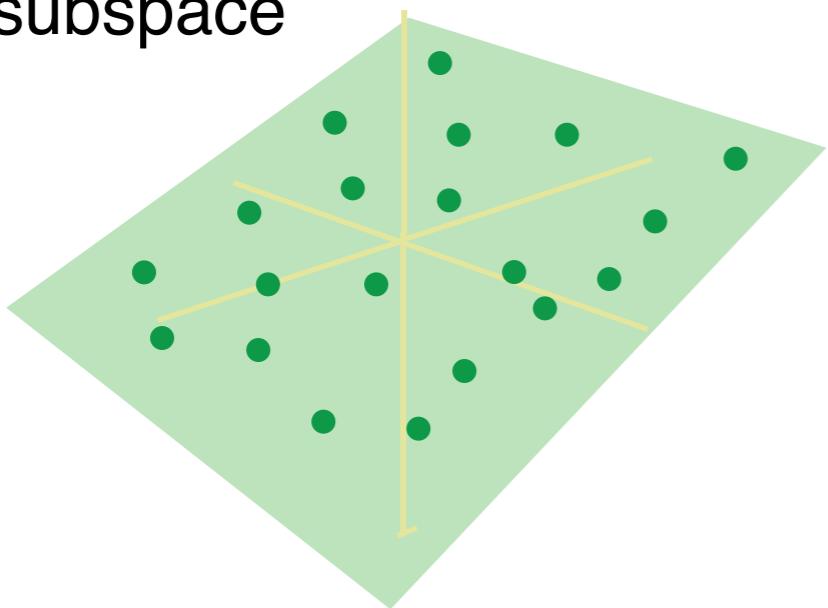
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



“low rank” approximation

low rank model

linear subspace
PCA



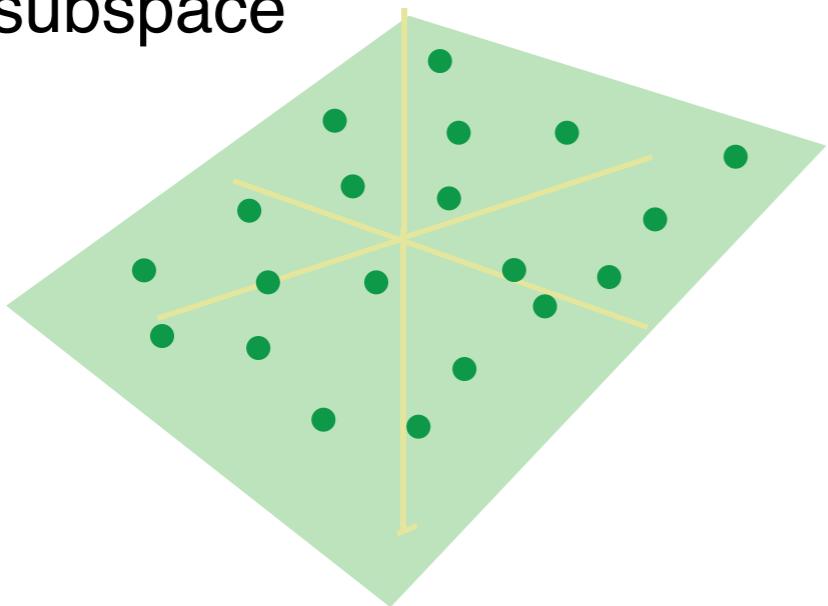
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



subject to = constraints

low rank model

linear subspace
PCA

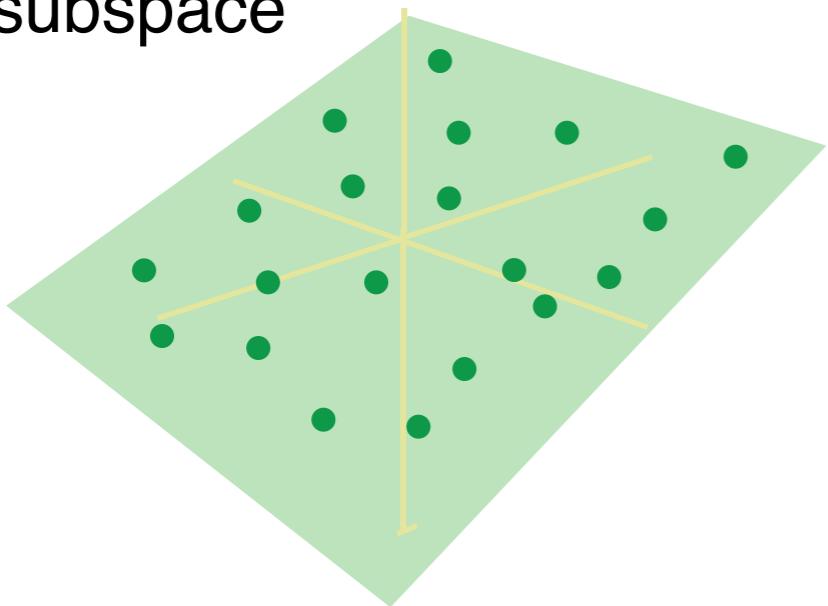


$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$

$$\text{rank}(\mathbf{A}) = ?$$

low rank model

linear subspace
PCA

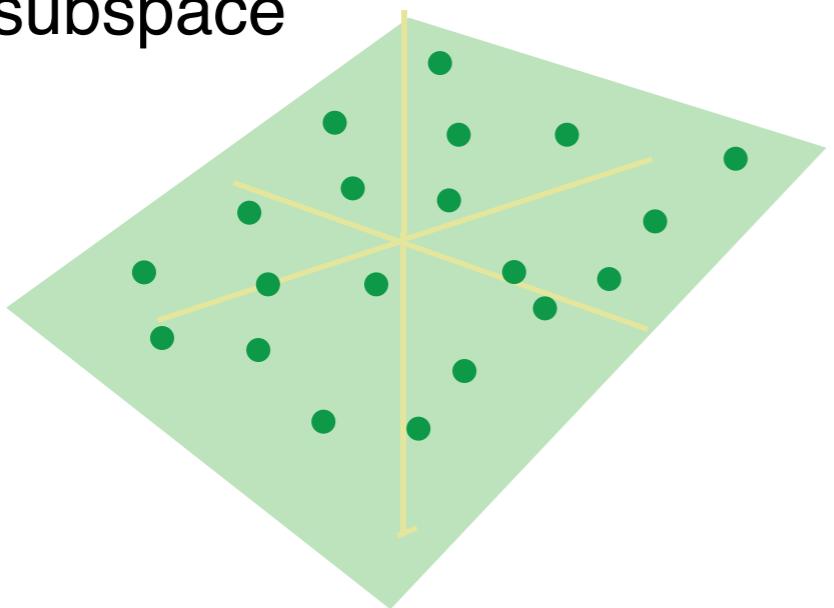


$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$

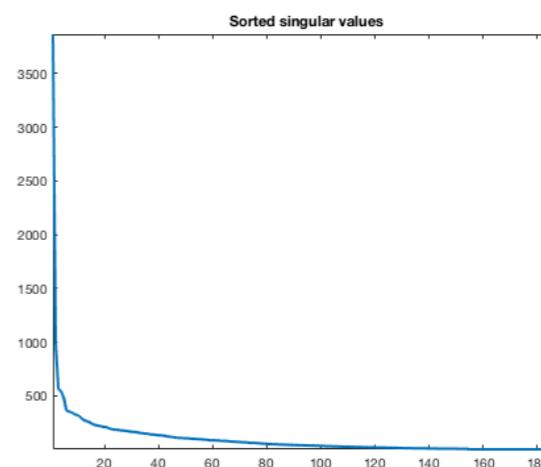
$$\text{rank}(\mathbf{A}) = ?$$

low rank model

linear subspace
PCA



$$[U, S, V] = \text{svd}(Y)$$



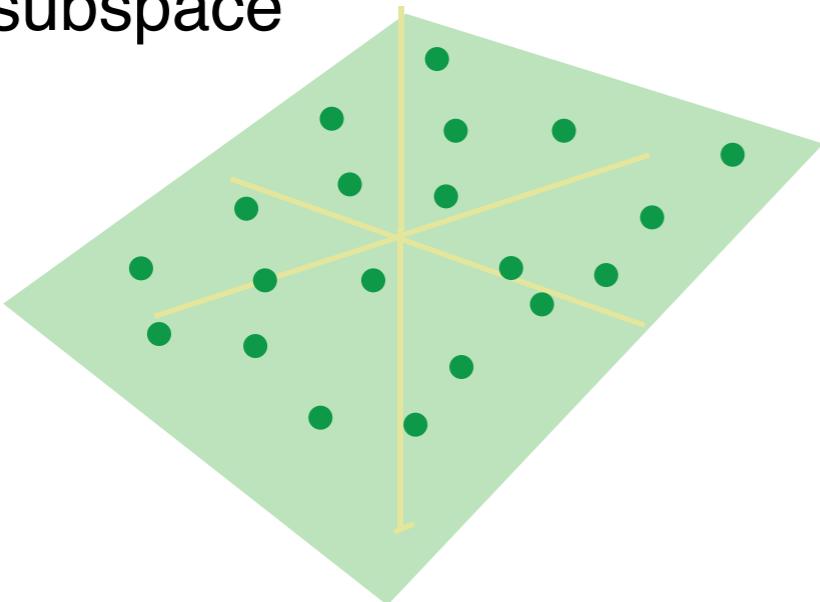
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



$$\mathbf{A} = \mathbf{U}_k \mathbf{S}_k \mathbf{V}_k^T \quad (\text{truncated SVD})$$

low rank model

linear subspace
PCA



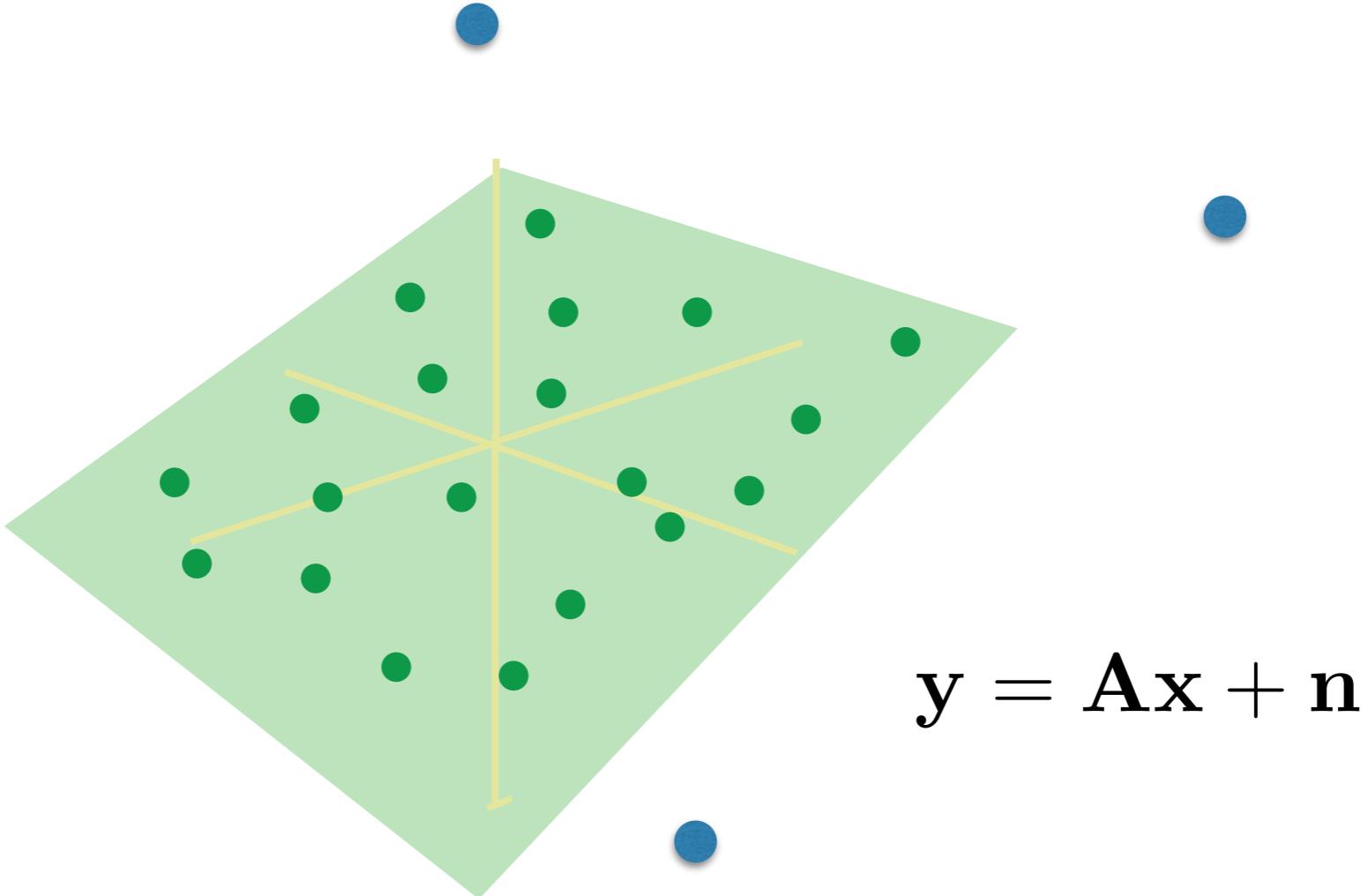
Covariance matrix

$$C = (\mathbf{Y} - \bar{\mathbf{y}})^T (\mathbf{Y} - \bar{\mathbf{y}})^T$$

PCA:

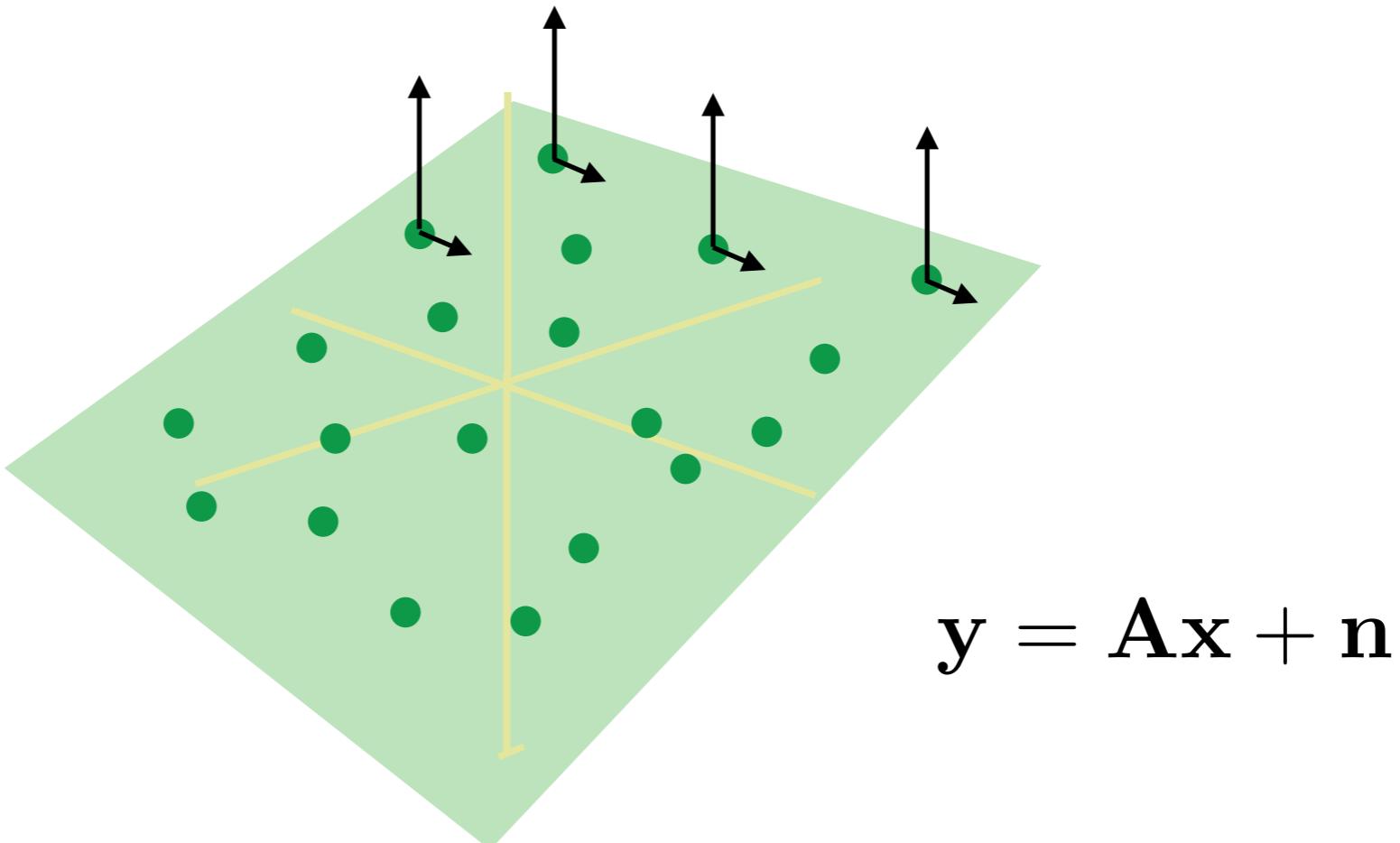
1. Compute the covariance matrix (C)
2. Compute eigenvalue decomposition of C
3. Output > top k eigenvectors and their eigenvalues

extensions of PCA



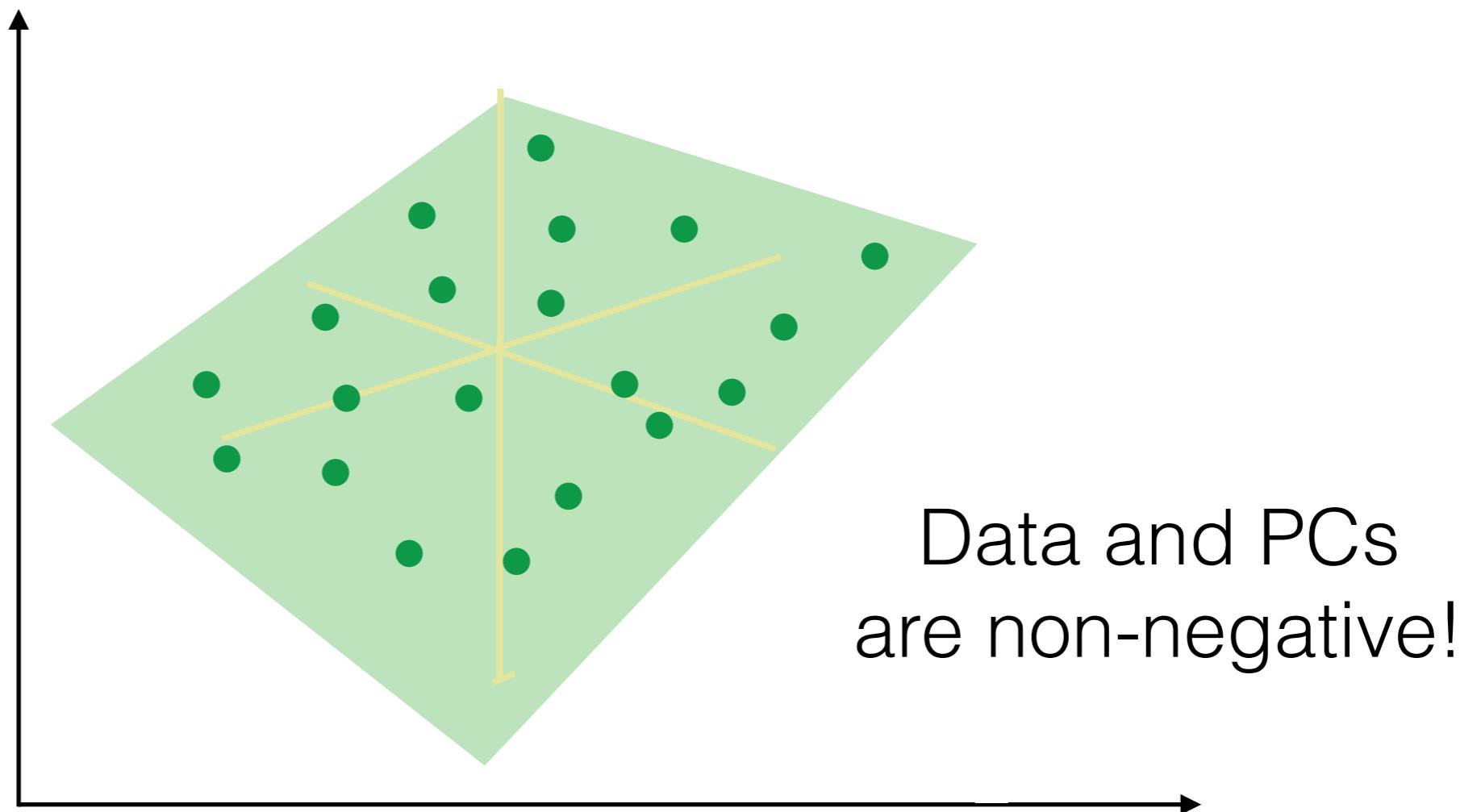
1. **Robust PCA - sparse LARGE errors**
2. Factor analysis (FA) - noise of unequal variance
3. Non-negative matrix factorization (NMF)

extensions of PCA



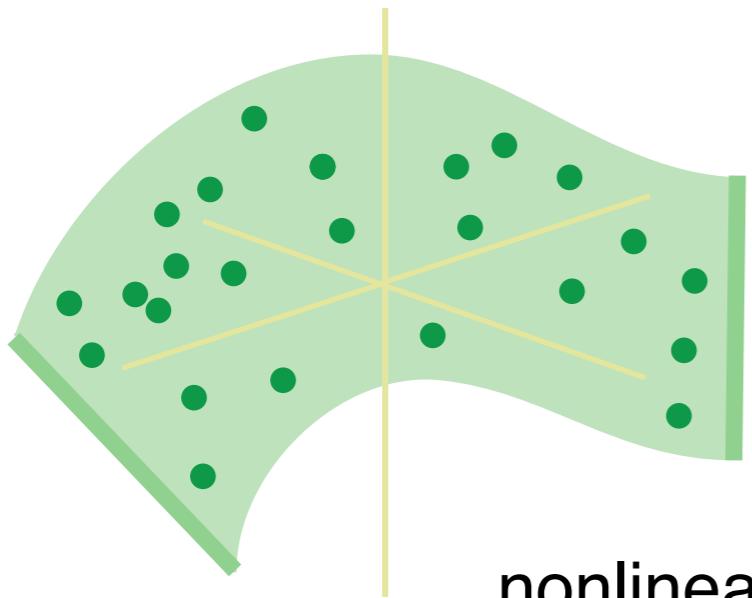
1. Robust PCA - sparse errors
2. **Factor analysis (FA) - noise of unequal variance**
3. Non-negative matrix factorization (NMF)

extensions of PCA



1. Robust PCA - sparse errors
2. Factor analysis (FA) - noise of unequal variance
- 3. Non-negative matrix factorization (NMF)**

nonlinear models (manifolds)



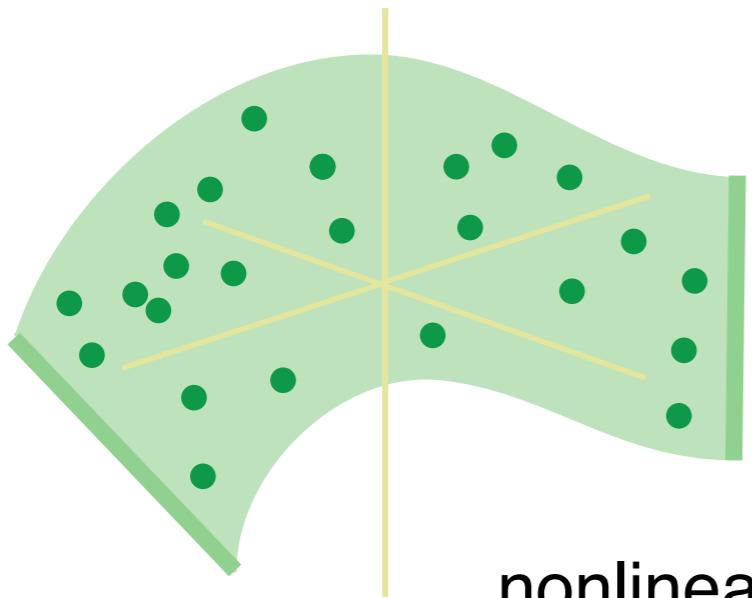
nonlinear manifold
Isomap, LLE

$$\min_{\mathcal{P}} |d(y_i, y_j) - d(\mathcal{P}y_i, \mathcal{P}y_j)|$$



distance between original data points

nonlinear models (manifolds)



nonlinear manifold
Isomap, LLE

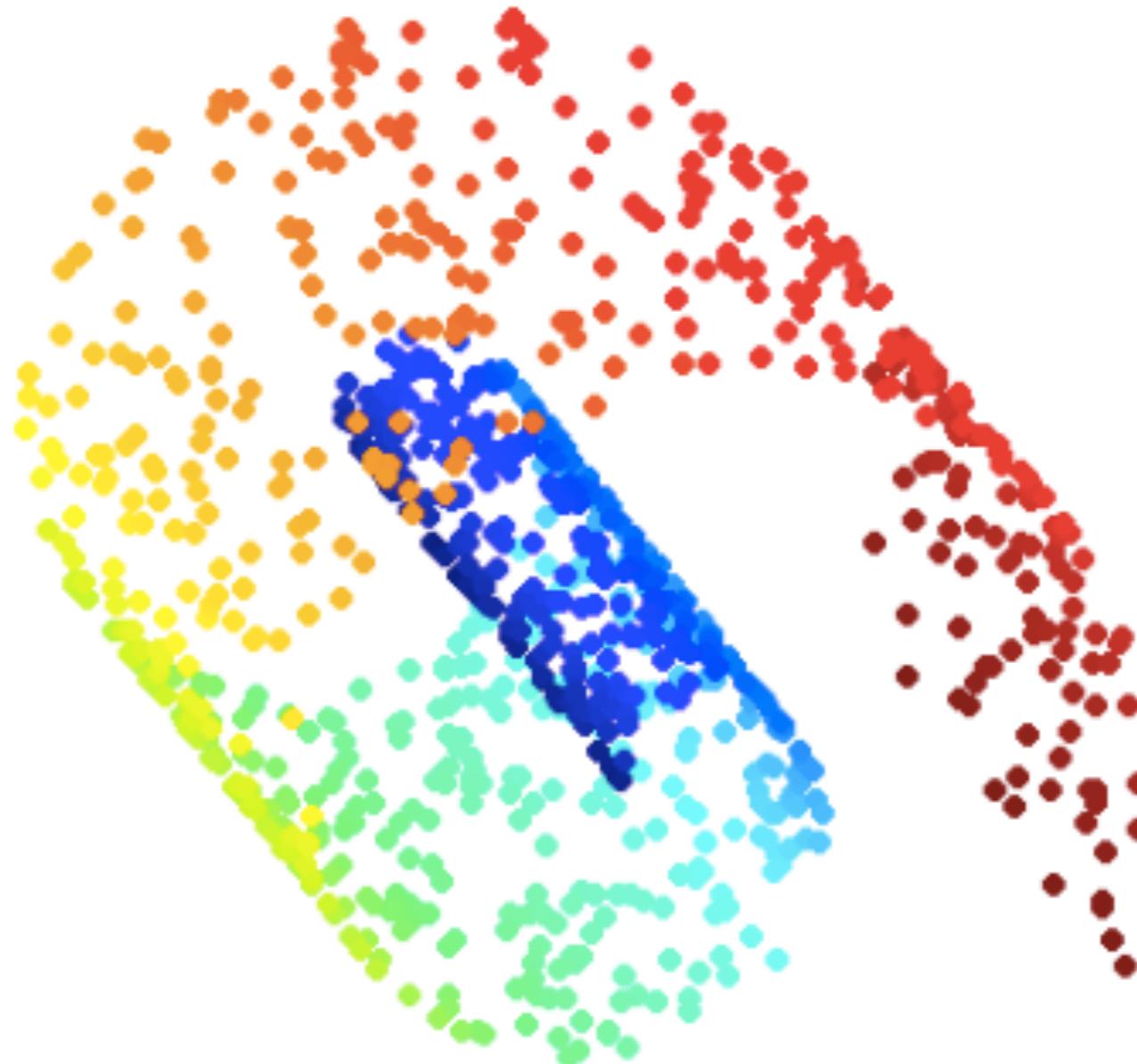
$$\min_{\mathcal{P}} |d(y_i, y_j) - d(\mathcal{P}y_i, \mathcal{P}y_j)|$$



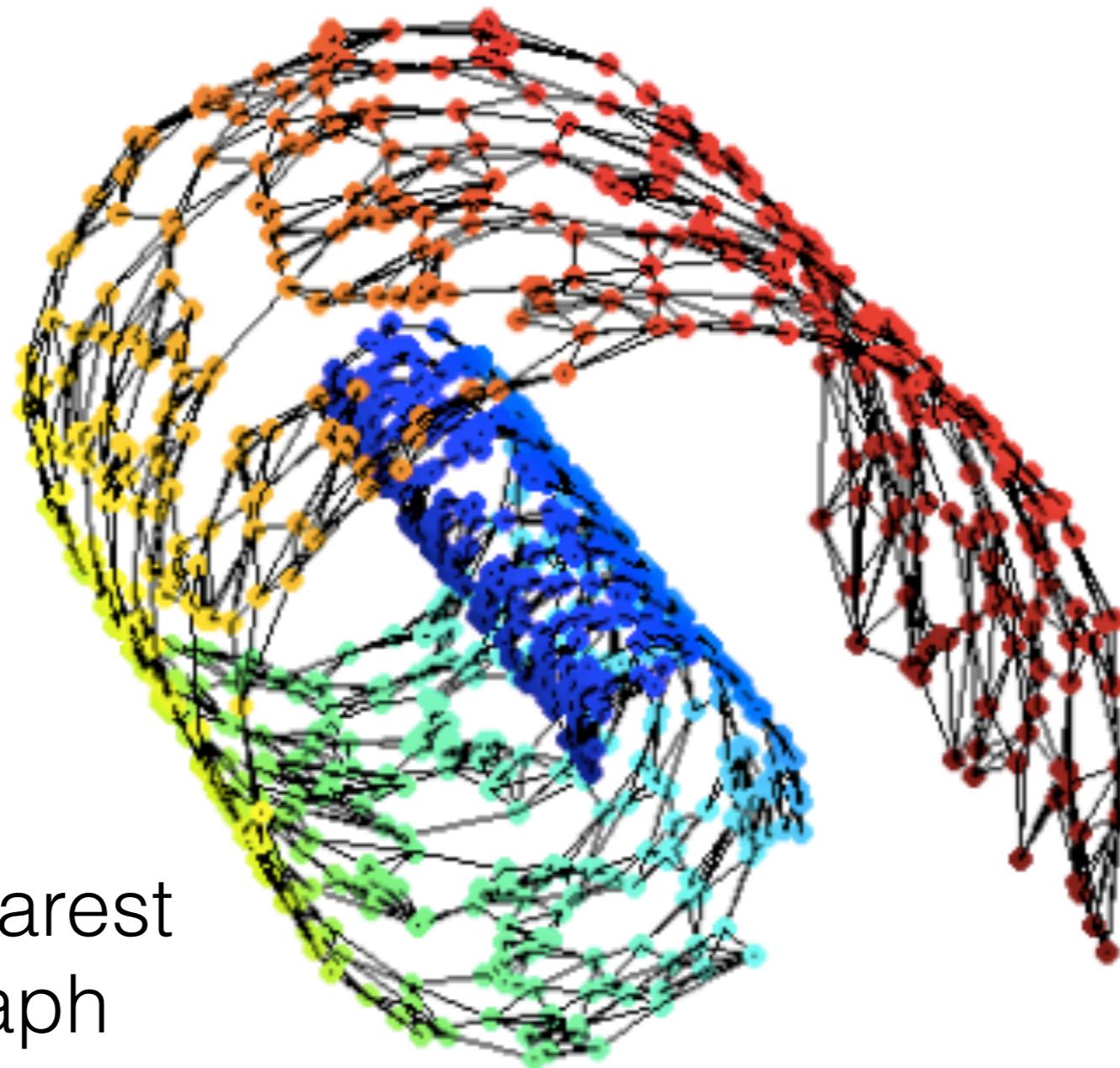
distance between projected data points

nonlinear models (manifolds)

swiss roll

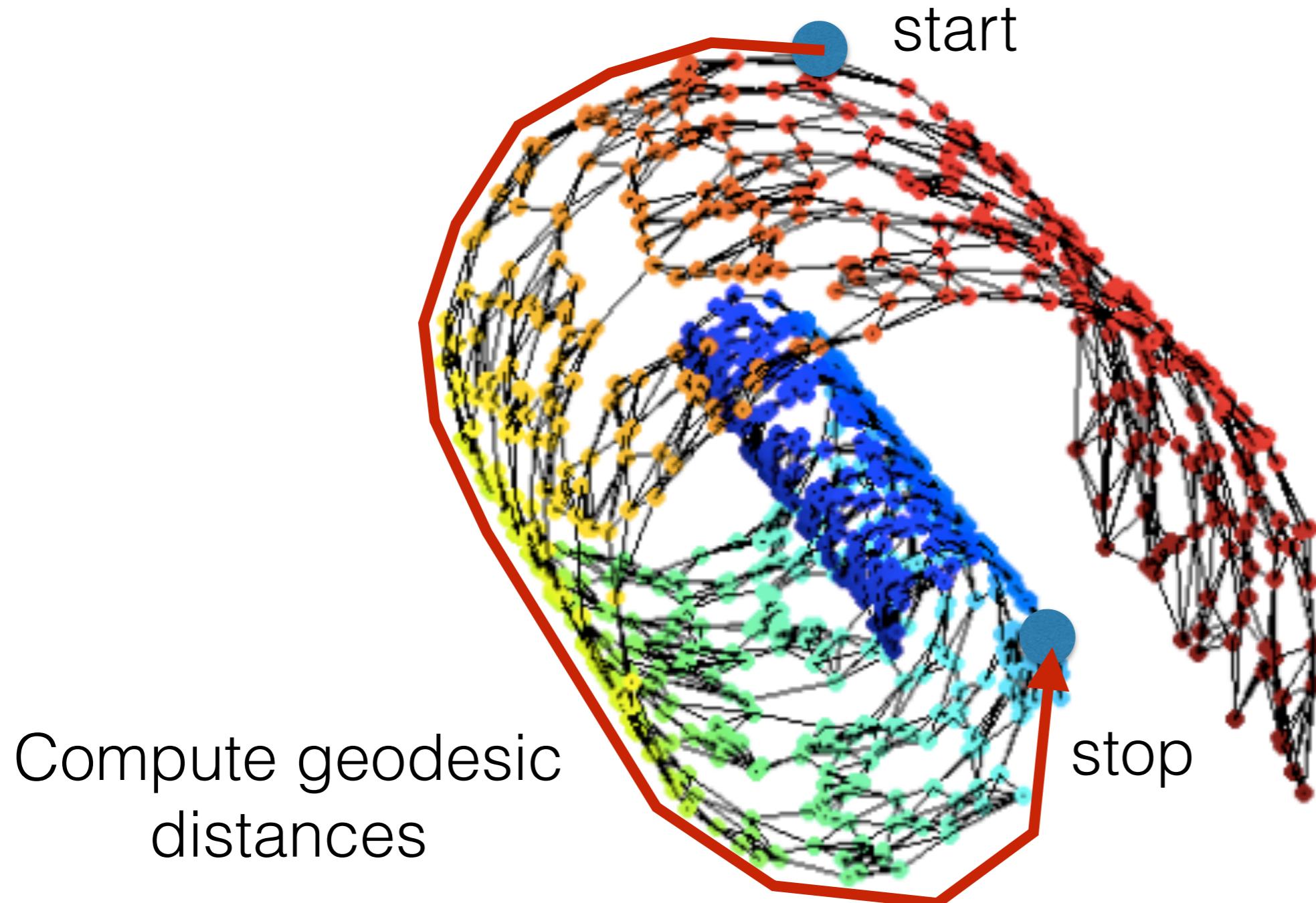


nonlinear models (manifolds)

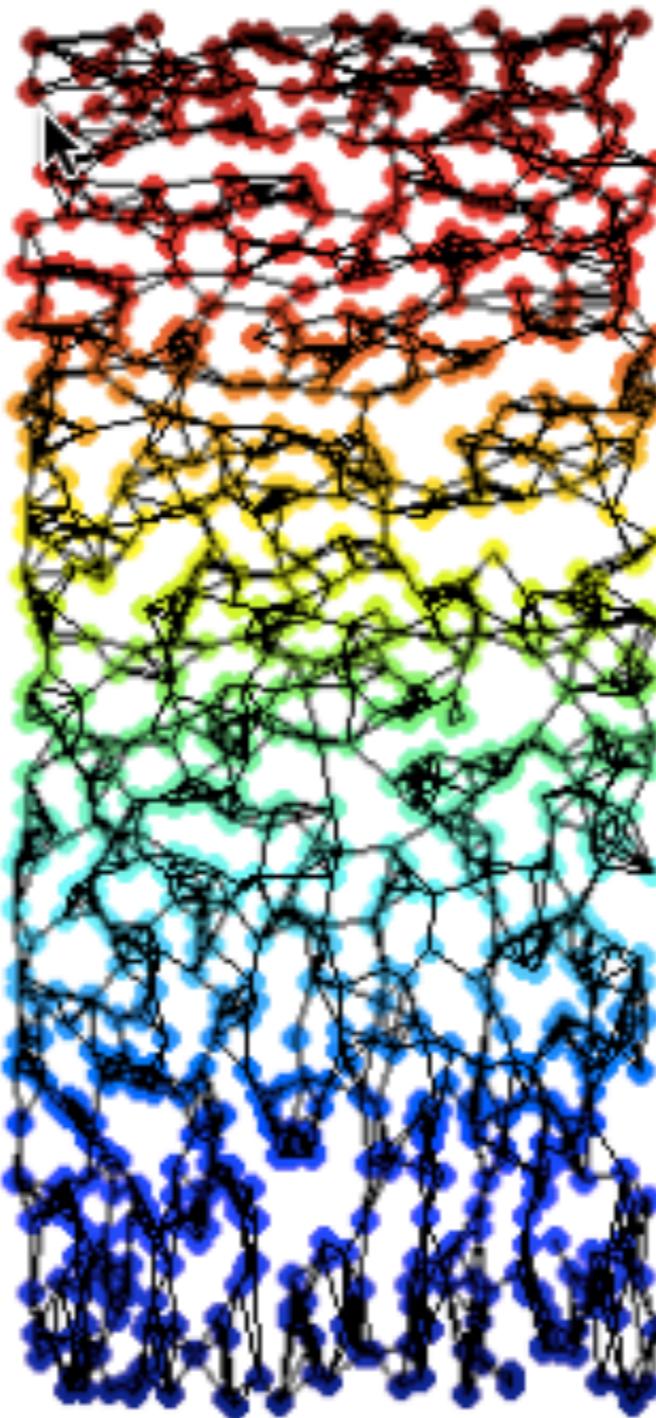


Compute k-nearest
neighbor graph

nonlinear models (manifolds)

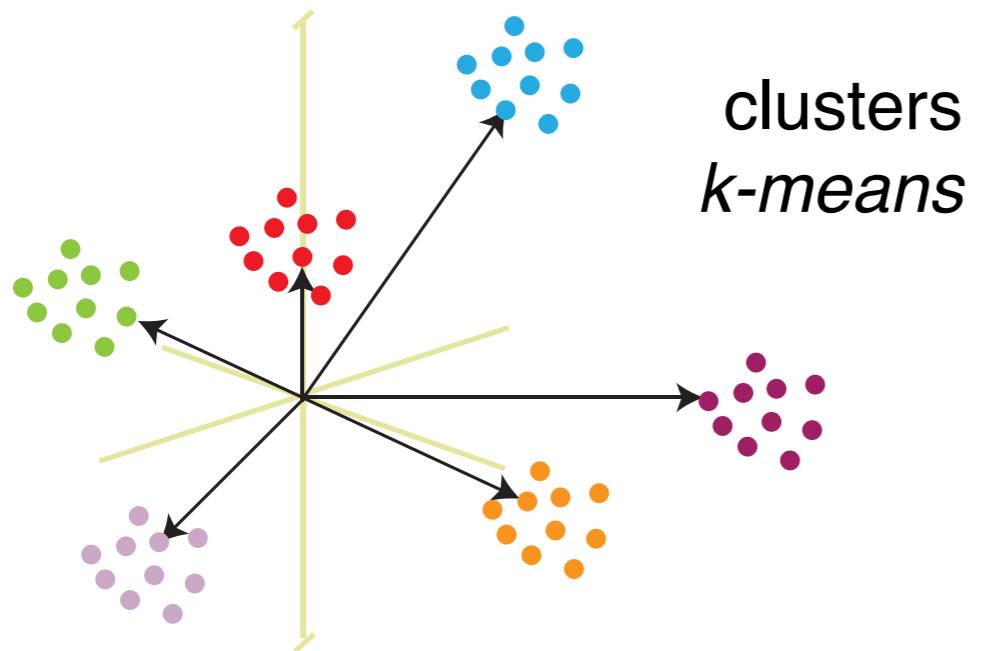


nonlinear models (manifolds)



Compute leading
eigenvectors

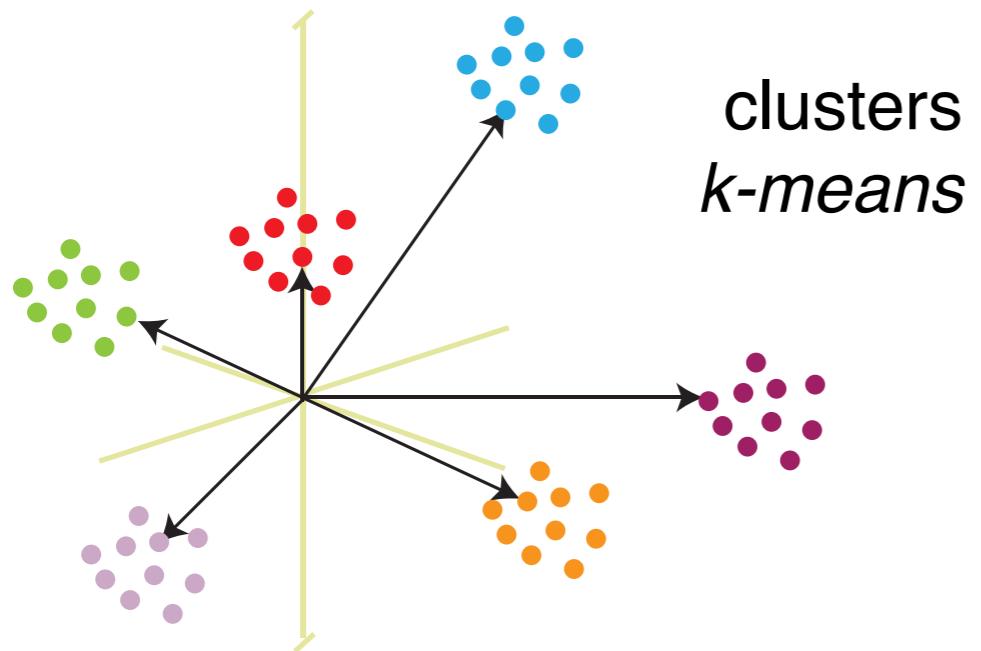
cluster model



$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_k} \sum_{j=1}^k \sum_{i \in \Omega_j} \|y_i - c_j\|_2$$

ith data point

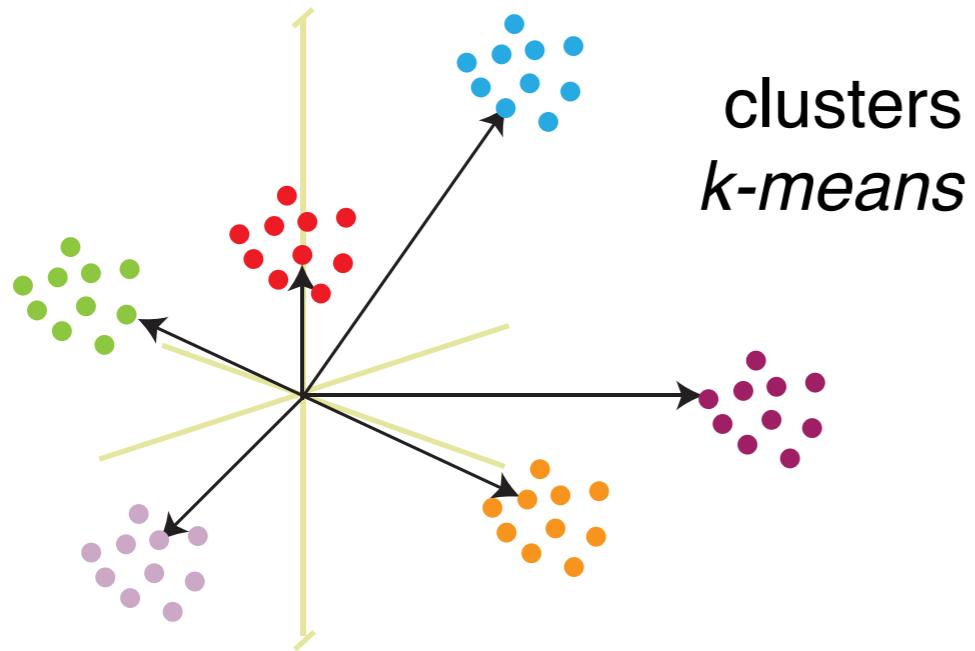
cluster model



$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_k} \sum_{j=1}^k \sum_{i \in \Omega_j} \|y_i - c_j\|_2$$

↑
jth cluster center

cluster model

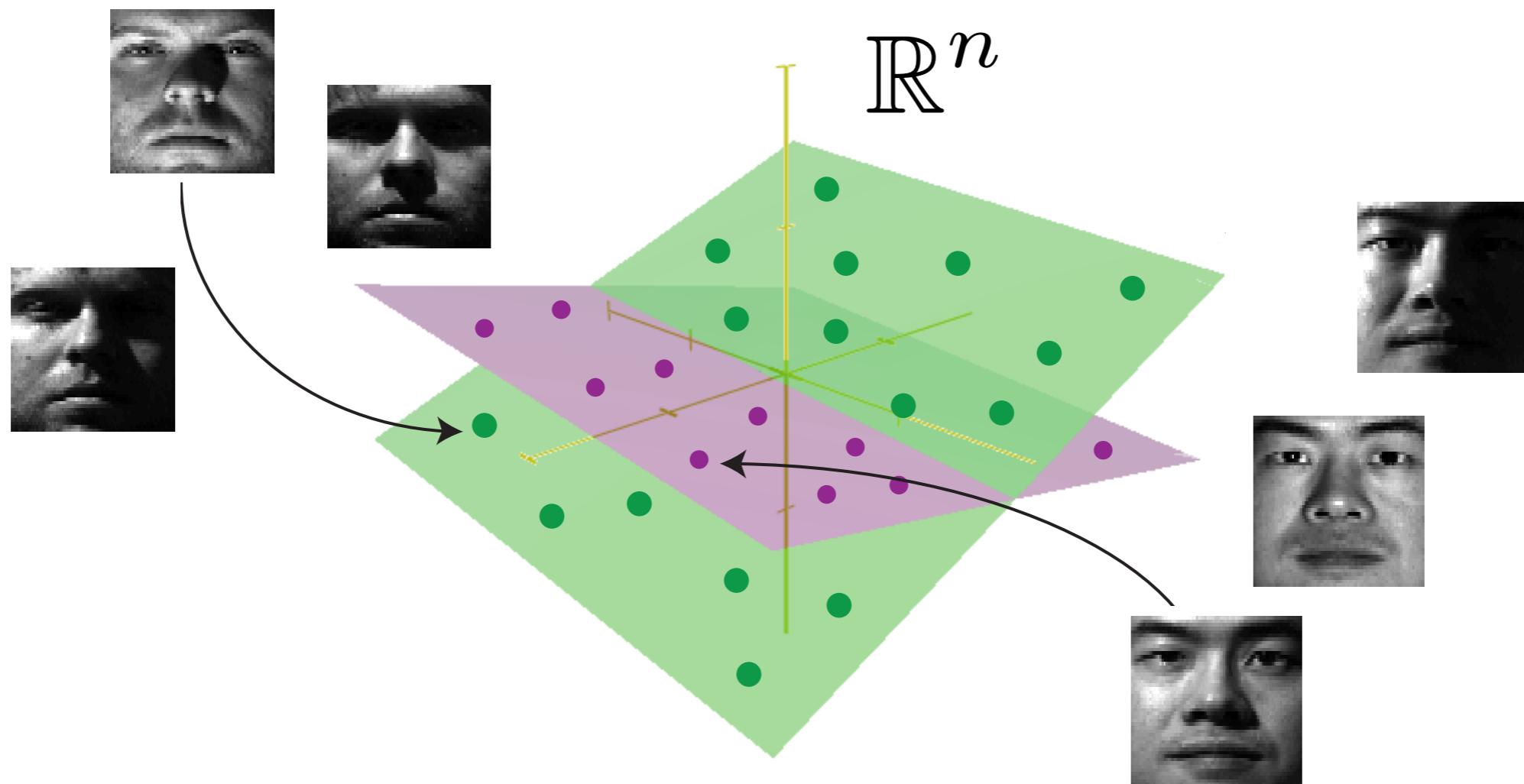


$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_k} \sum_{j=1}^k \sum_{i \in \Omega_j} \|y_i - c_j\|_2$$

kmeans:

1. Randomly initialize cluster centers
2. Assign each data point to its closest cluster center
3. Update cluster centers (mean of all assigned points)
4. Iterate steps 2-3 until convergence

union of subspaces

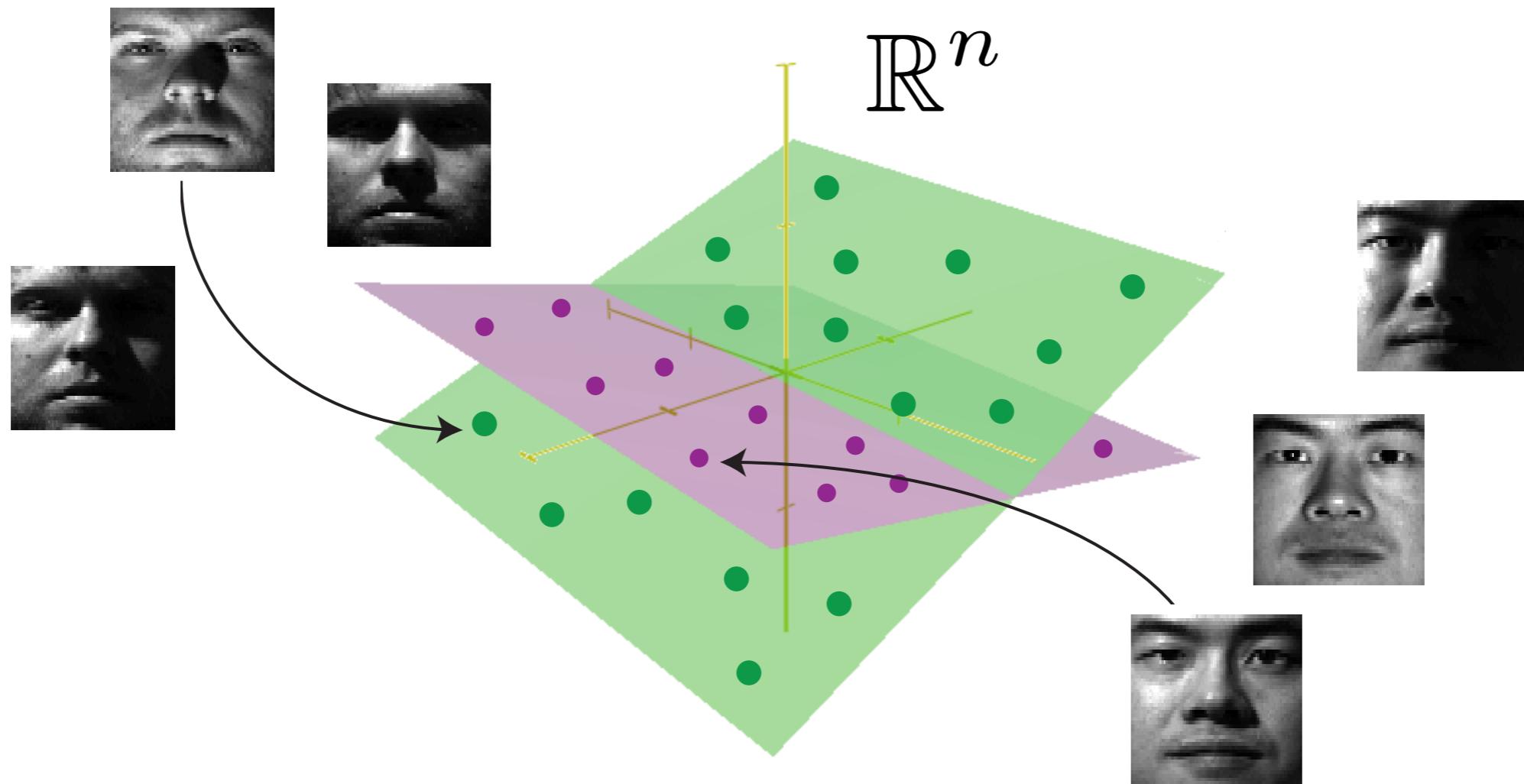


$$\min_{\mathbf{A}_i, \Omega_i} \sum \|\mathbf{Y}_{\Omega_i} - \mathbf{A}_i\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}_i) \leq k_i$$



subset of data in ith subspace

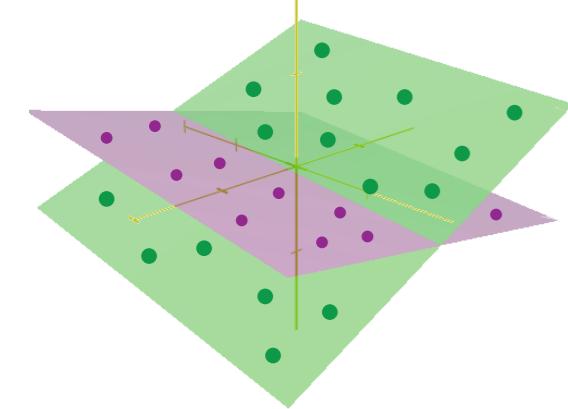
union of subspaces



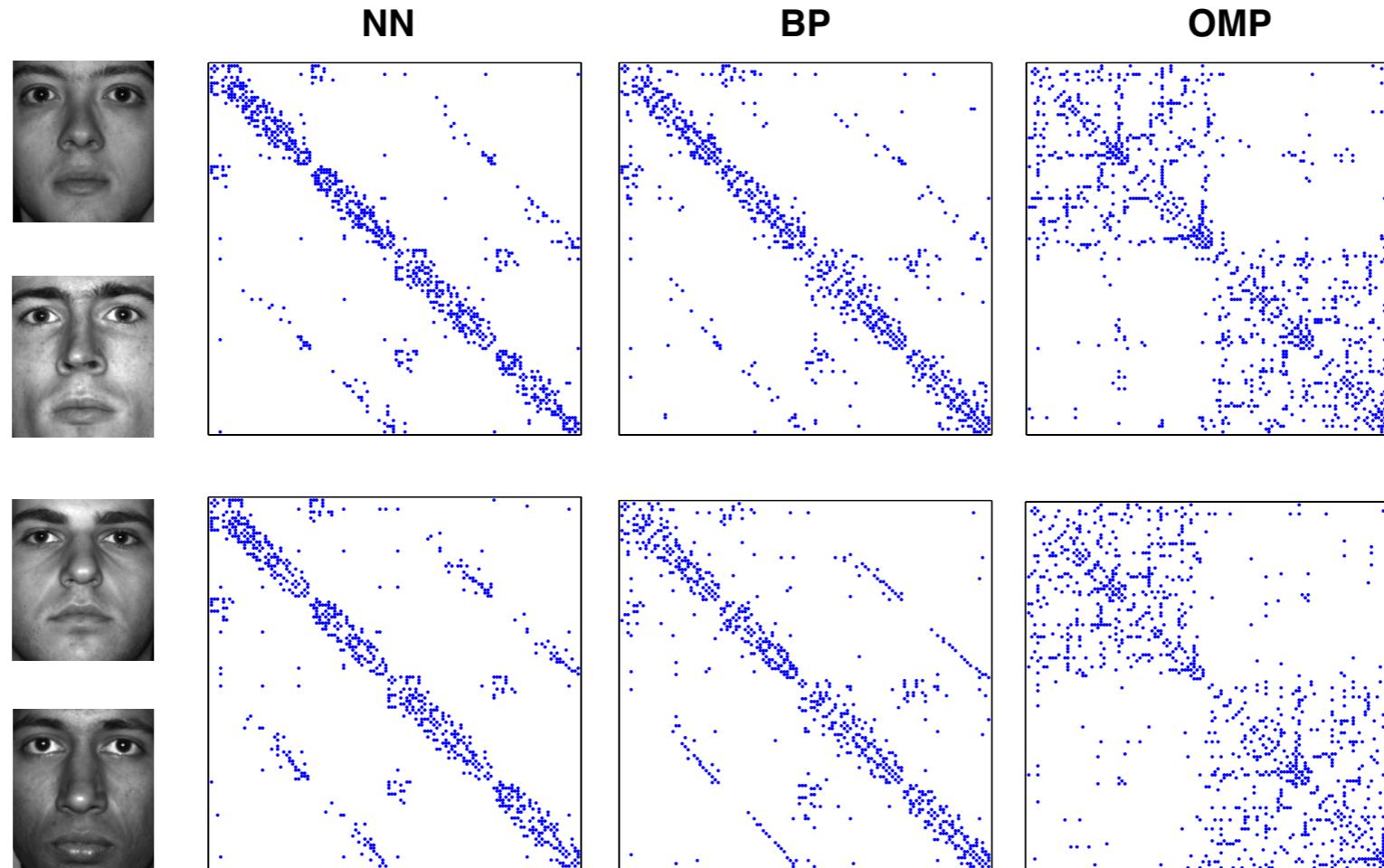
$$\min_{\mathbf{A}_i, \Omega_i} \sum \|\mathbf{Y}_{\Omega_i} - \mathbf{A}_i\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}_i) \leq k_i$$



low rank approx of ith cluster



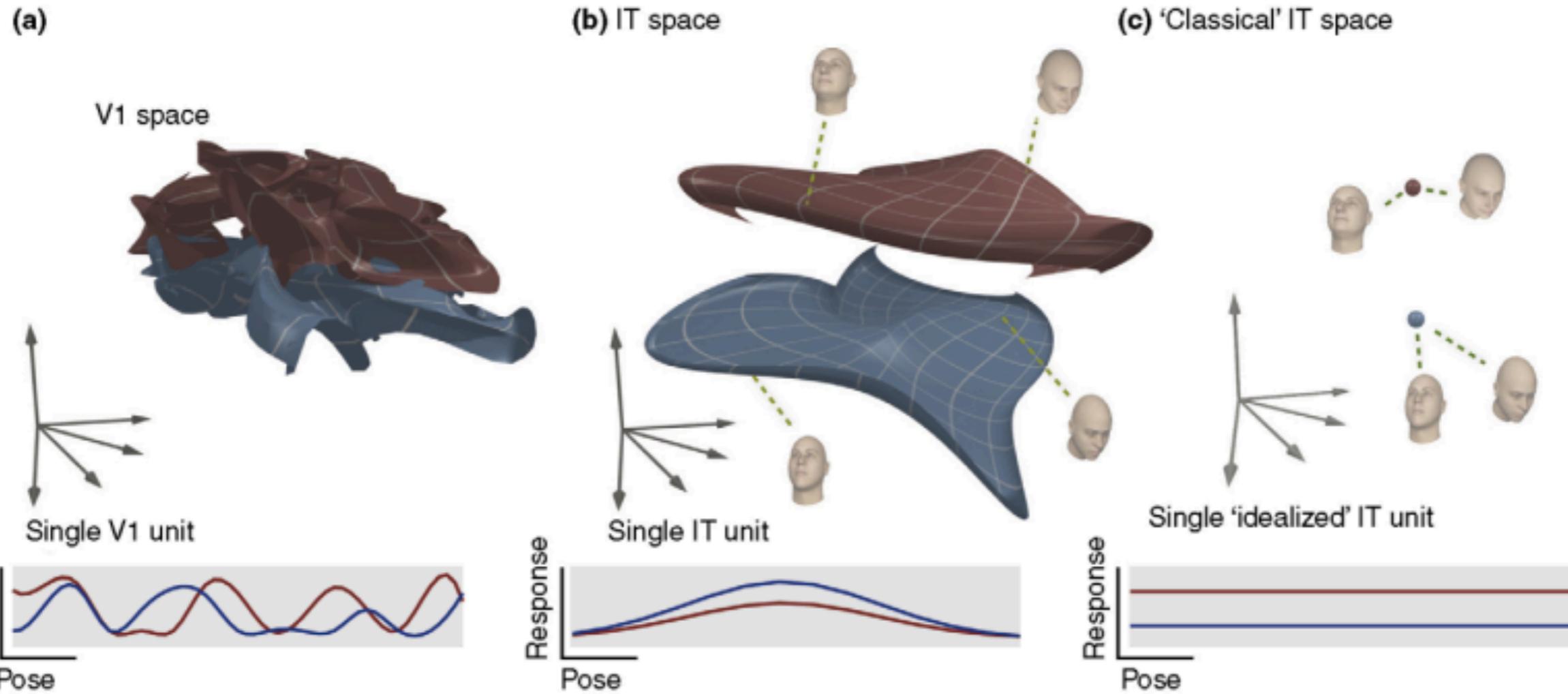
union of subspaces



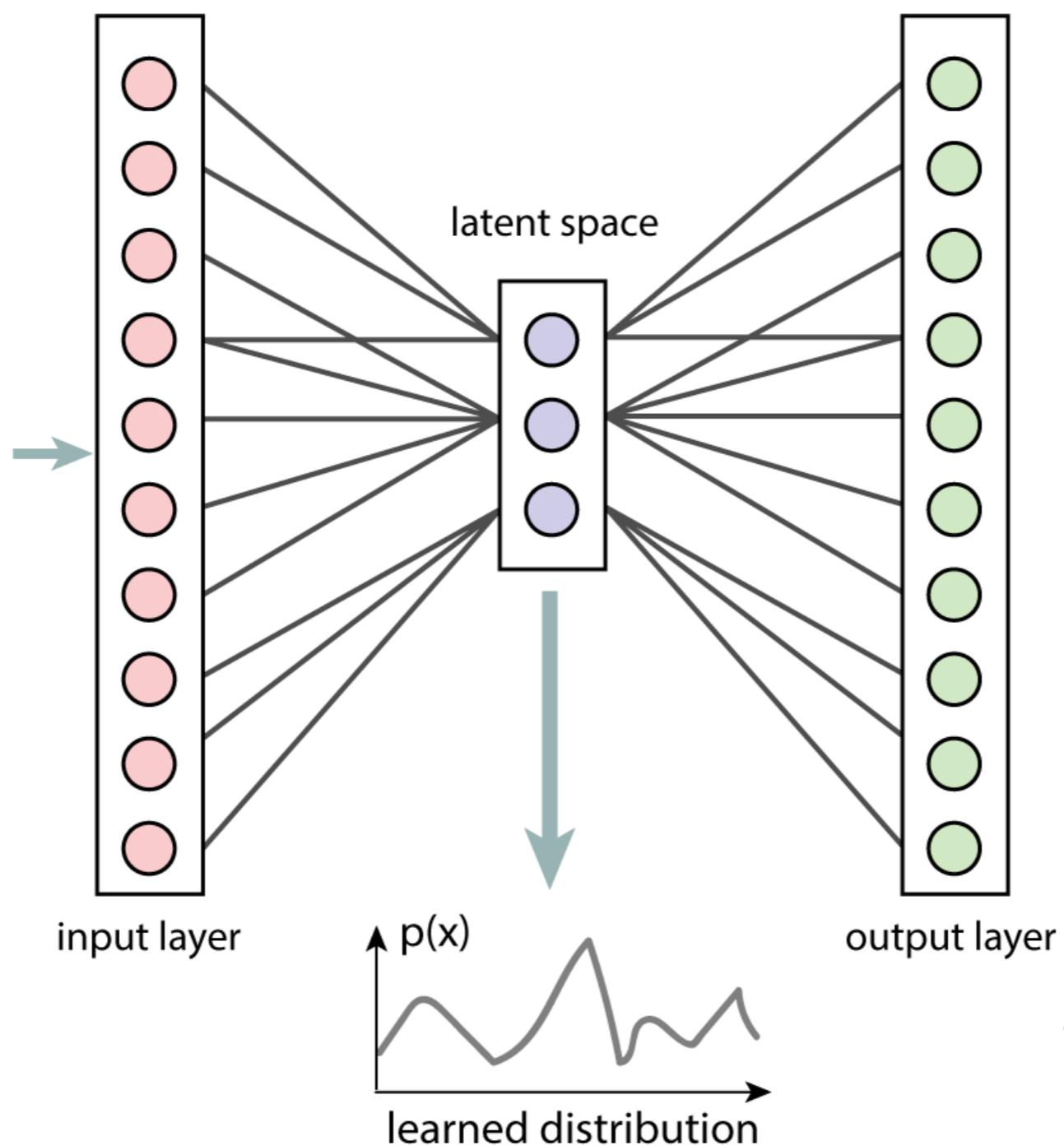
sparse subspace clustering (SSC):

1. Compute the subspace affinity matrix (C)
2. Cluster the affinity matrix C
3. For each subspace cluster, run SVD and get low rank approximation

“tangled” manifolds

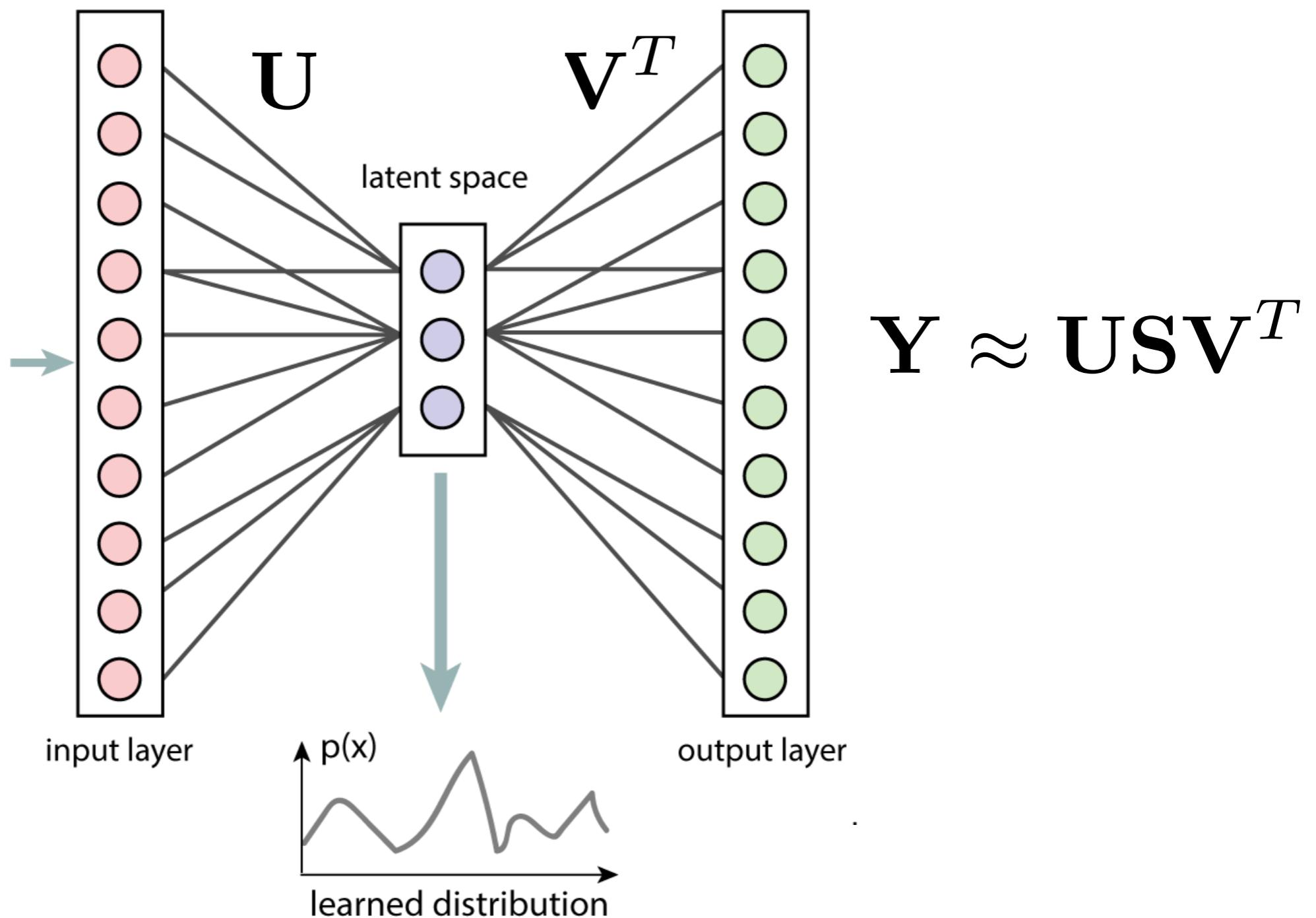


autoencoders



$$\min_f \quad f(\mathbf{Y}_{in}, \mathbf{Y}_{out})$$

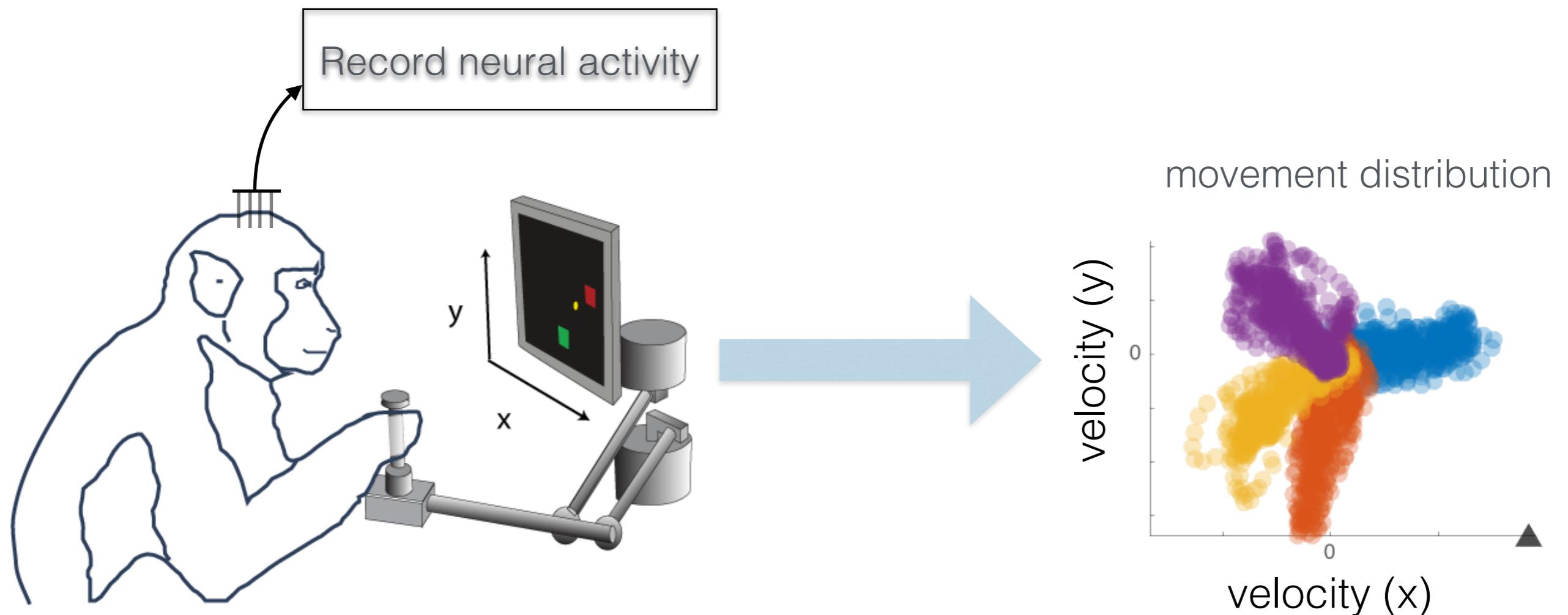
linear autoencoder -> PCA



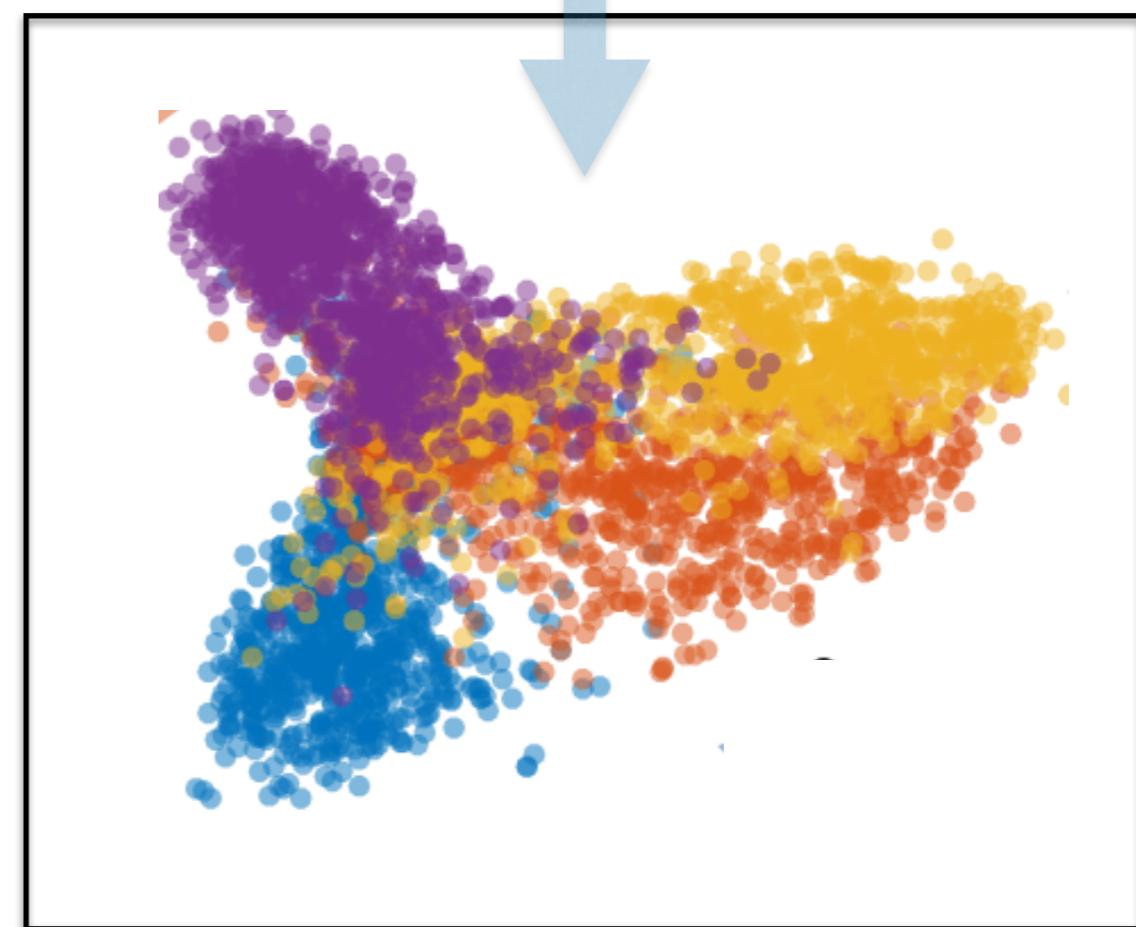
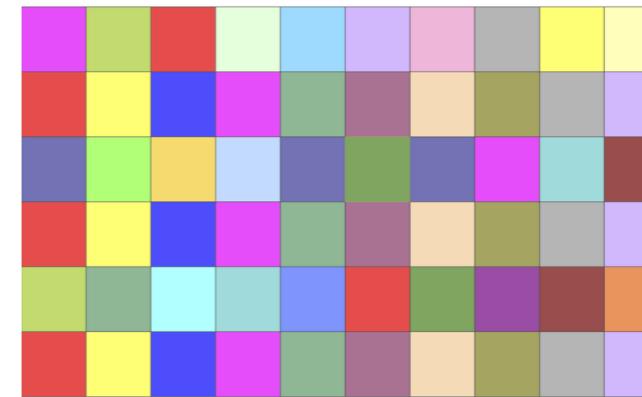
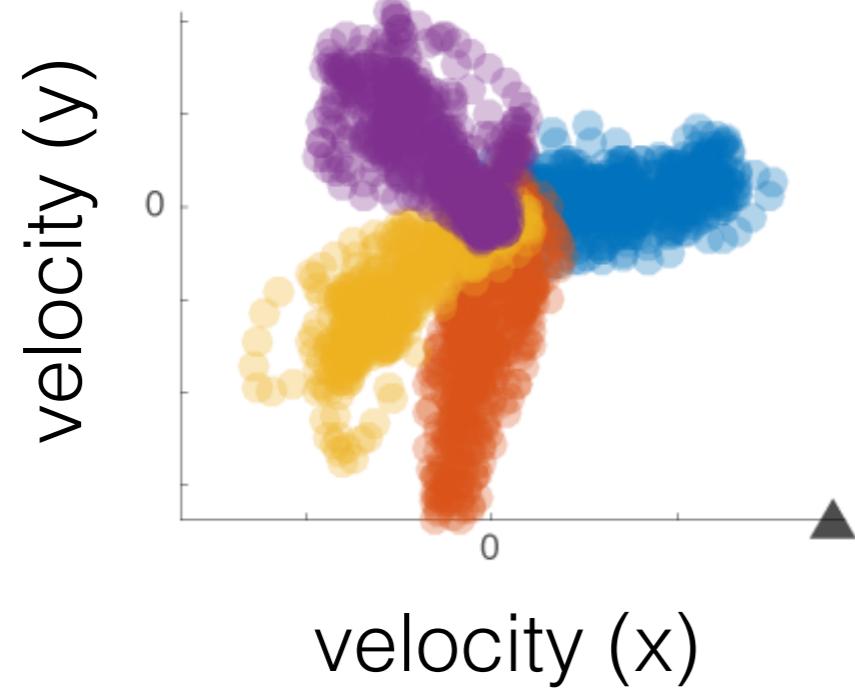
$$\min_f \quad f(\mathbf{Y}_{in}, \mathbf{Y}_{out})$$

application to
movement decoding

movement decoding

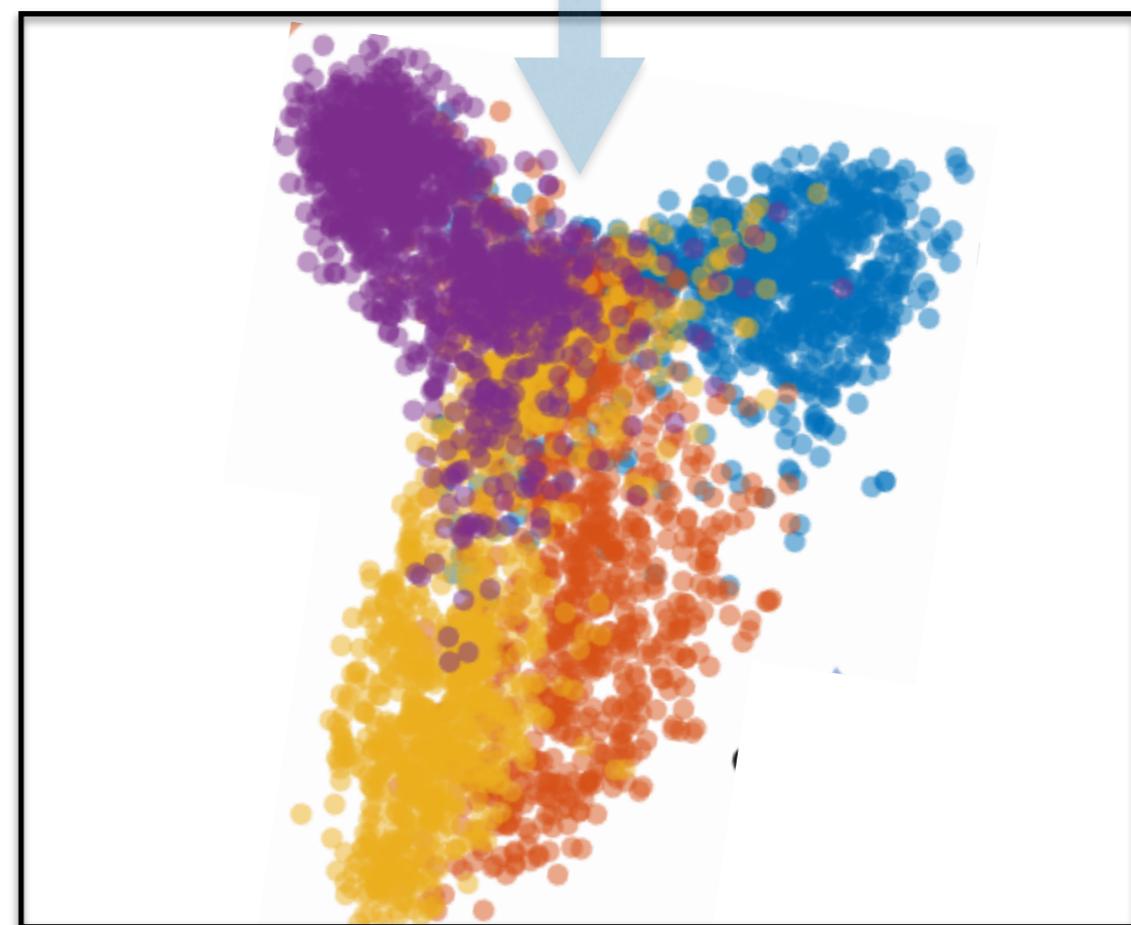
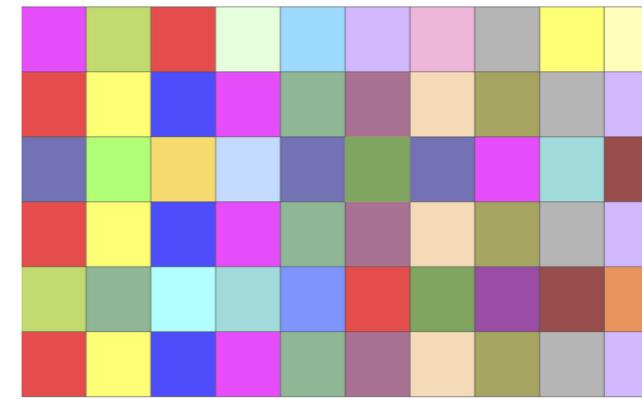
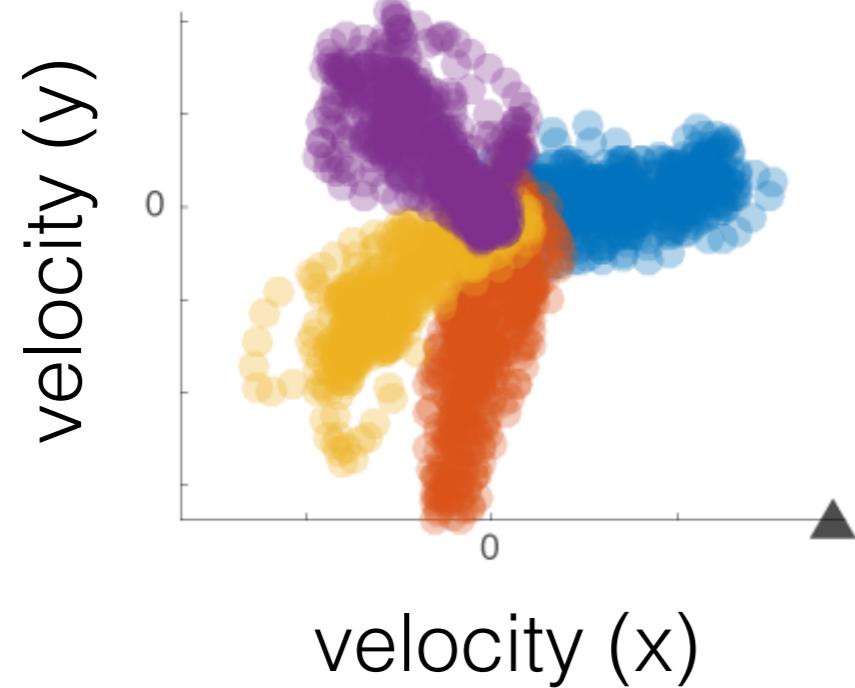


neural responses are low-d



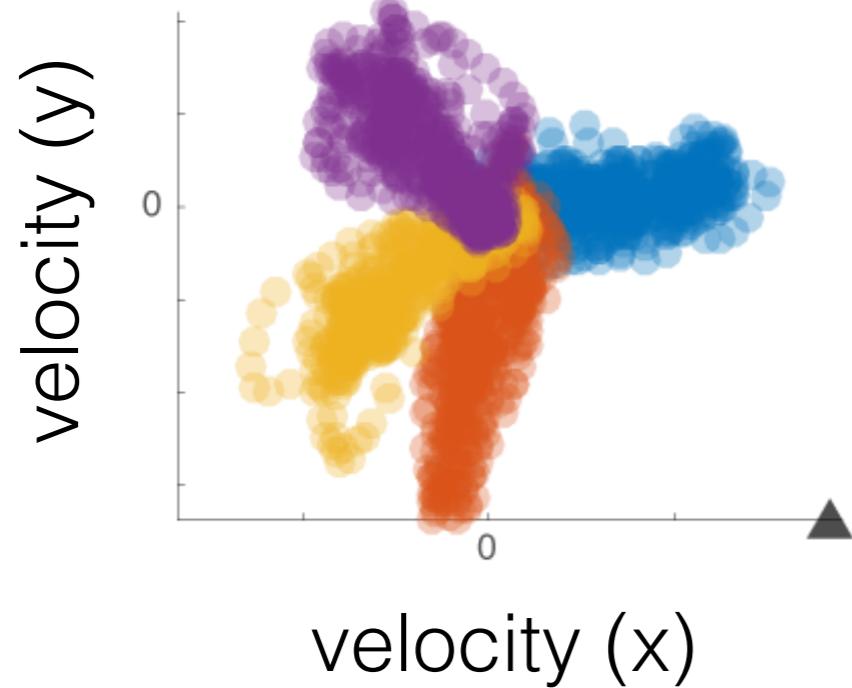
good low-d representation

neural responses are low-d

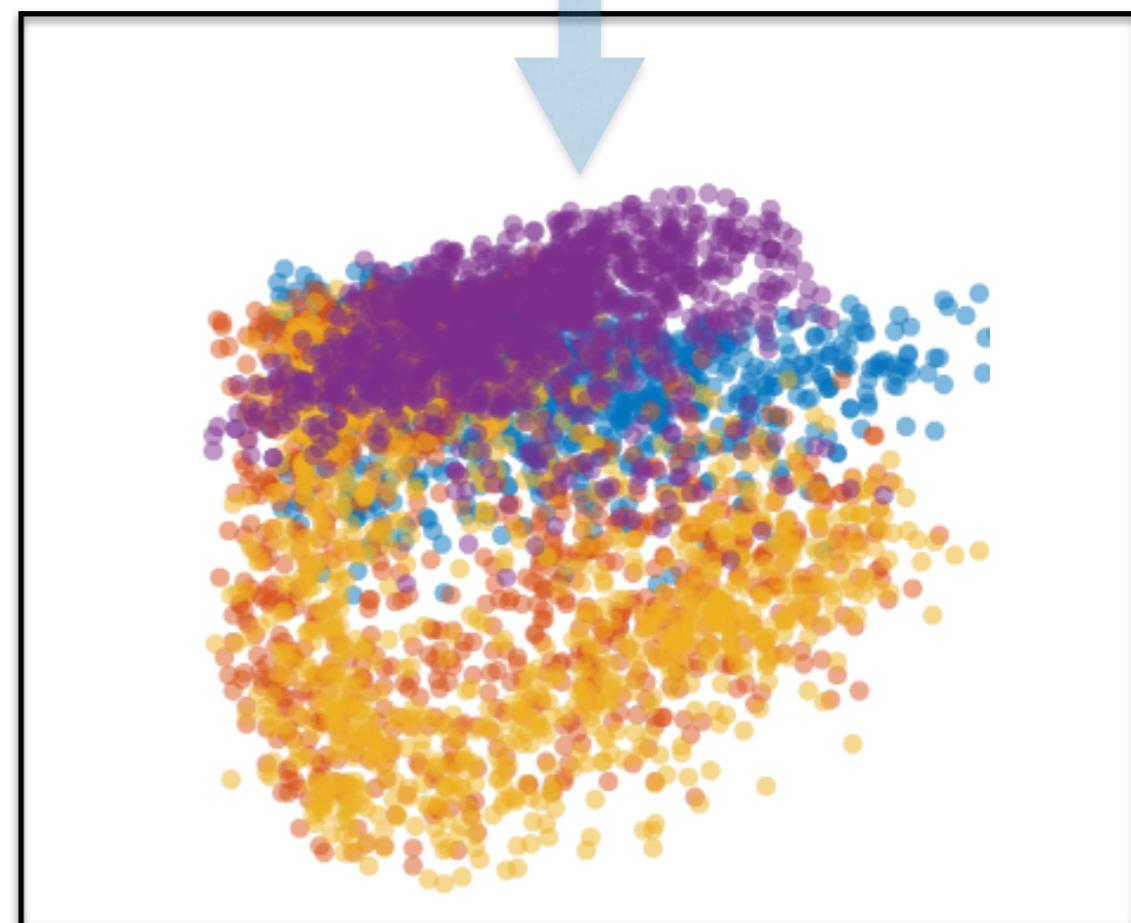
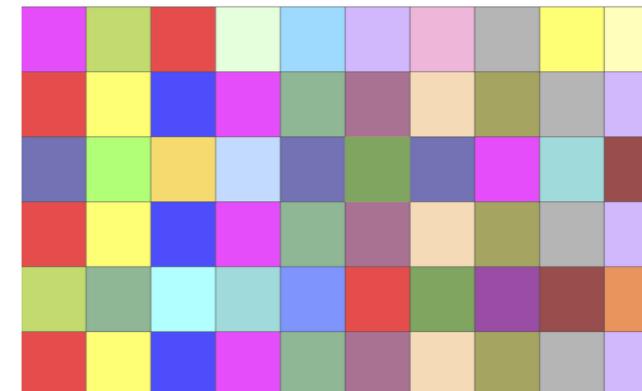


good low-d representation

neural responses are low-d

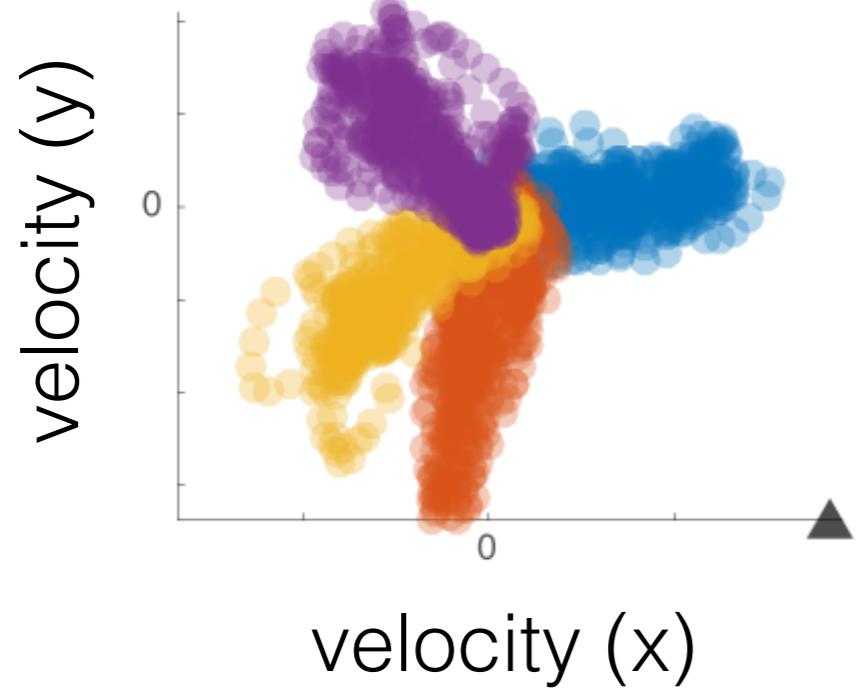


challenge: signal and noise structure vary!

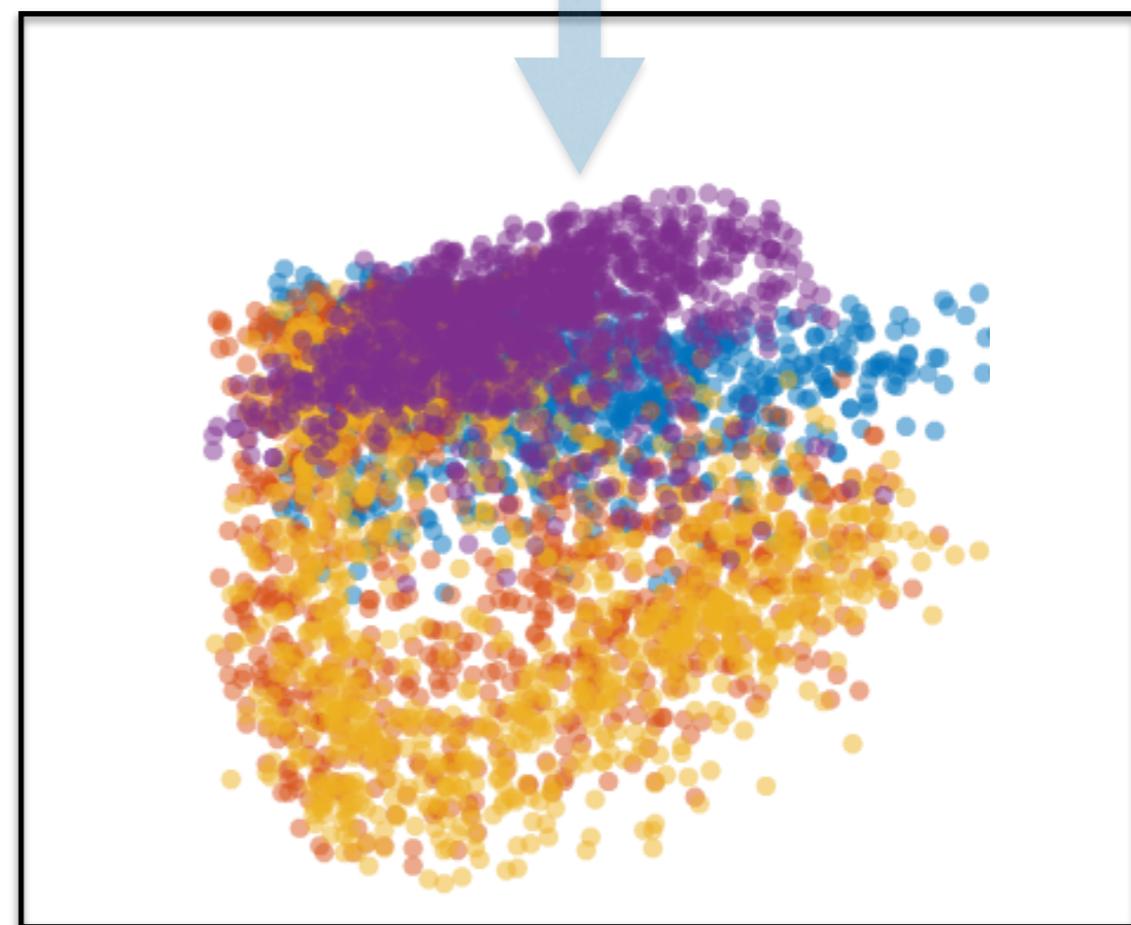
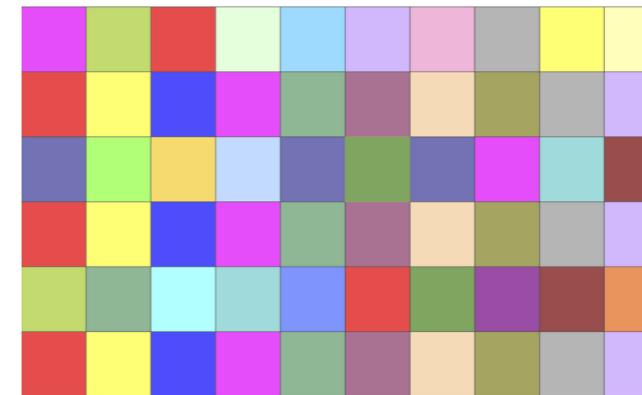


bad low-d representation

neural responses are low-d

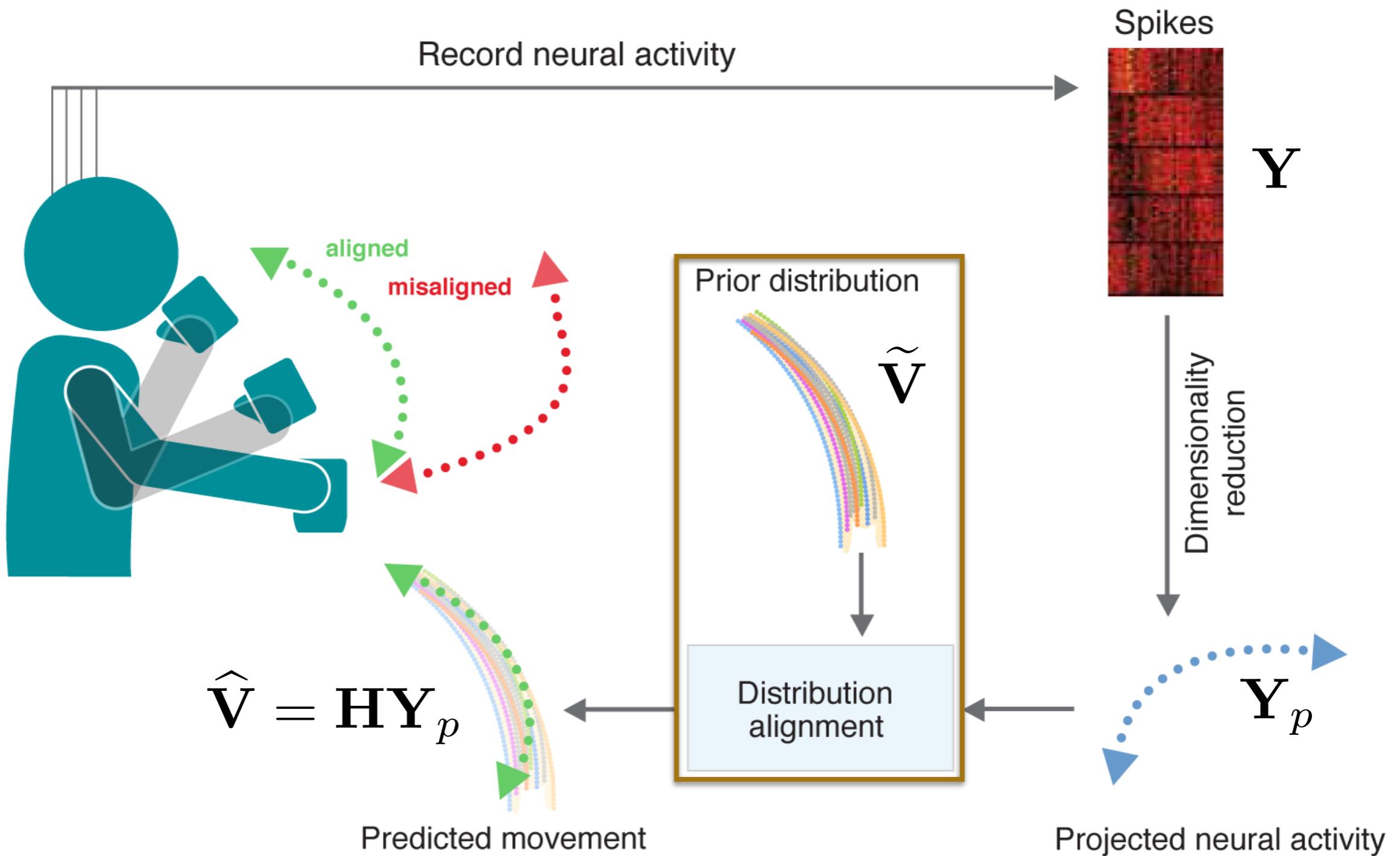


solution: leverage distribution of known movements

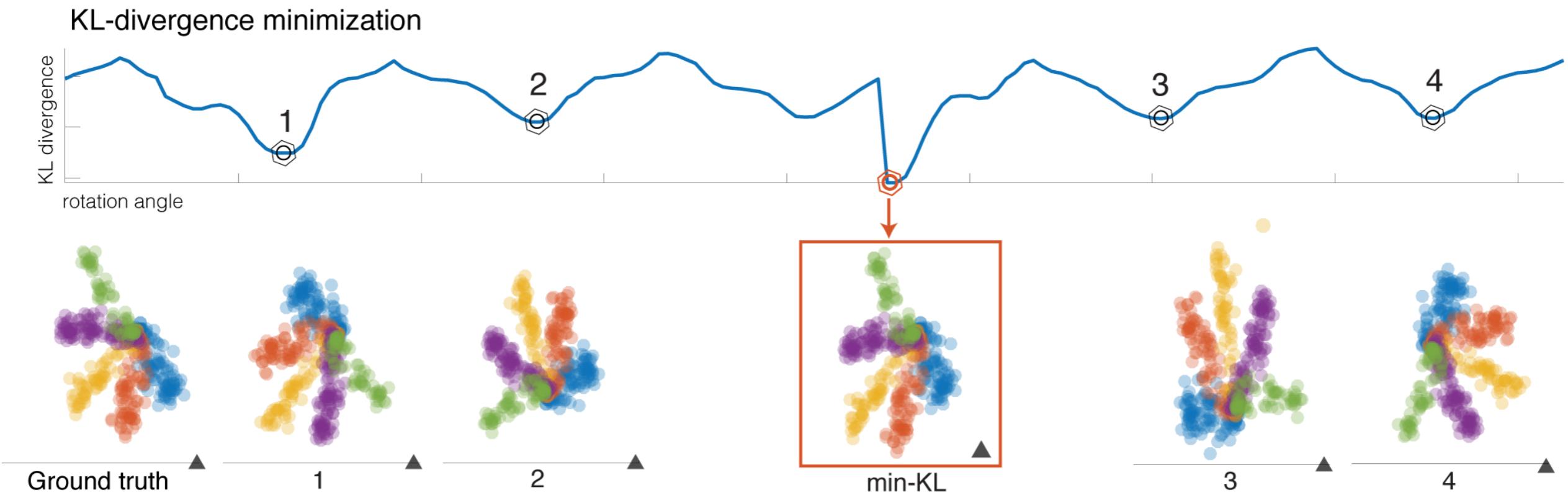


bad low-d representation

distribution alignment approach

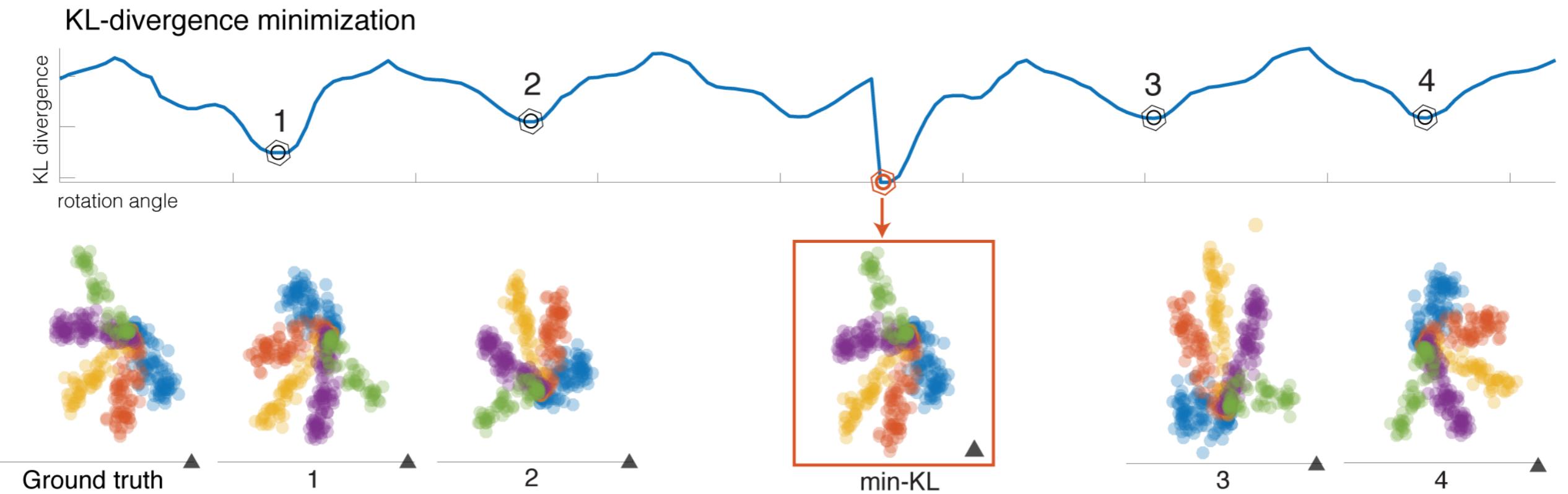


KL-divergence minimization



goal: align neural activities with prior movement distribution

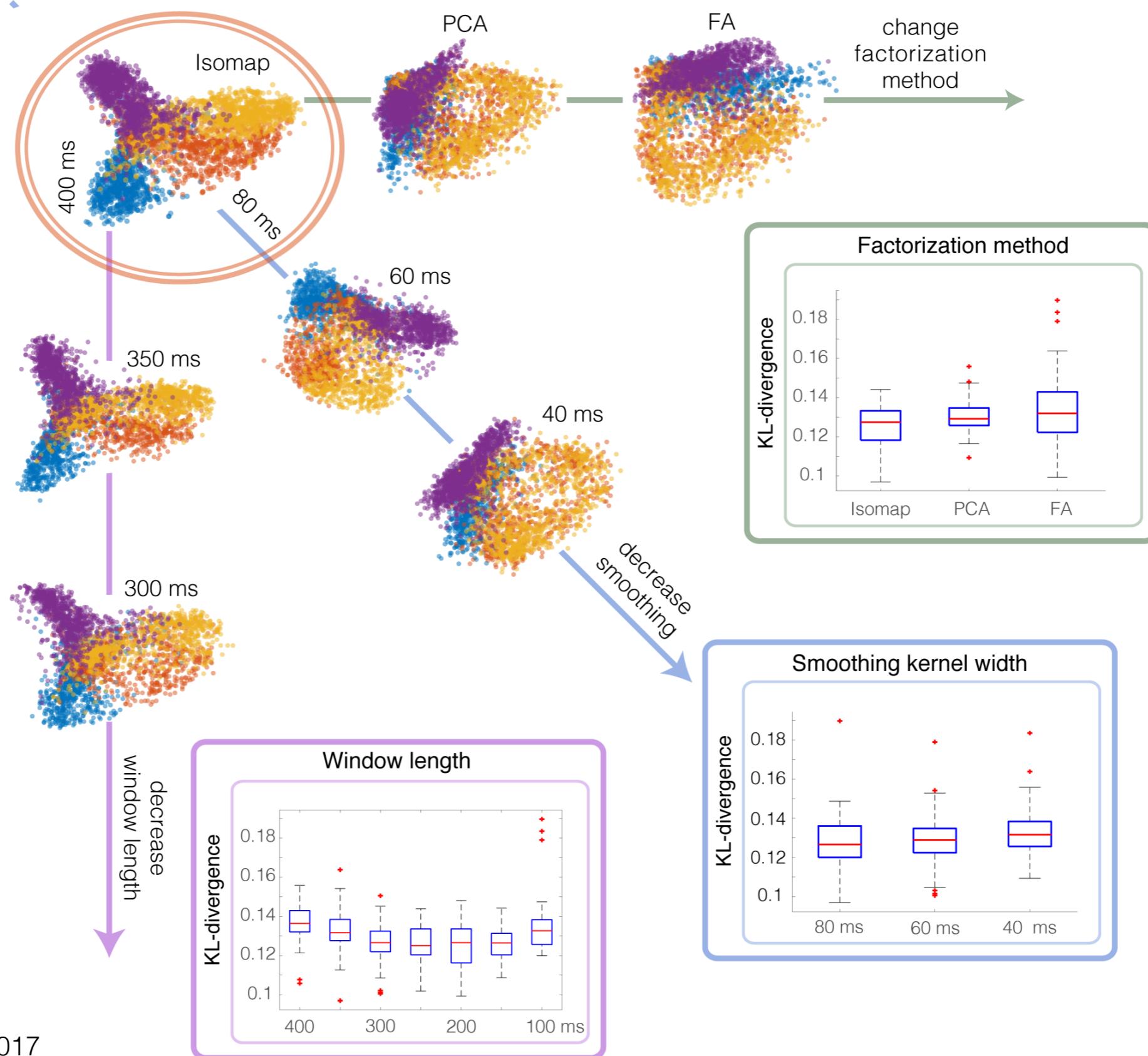
KL-divergence minimization



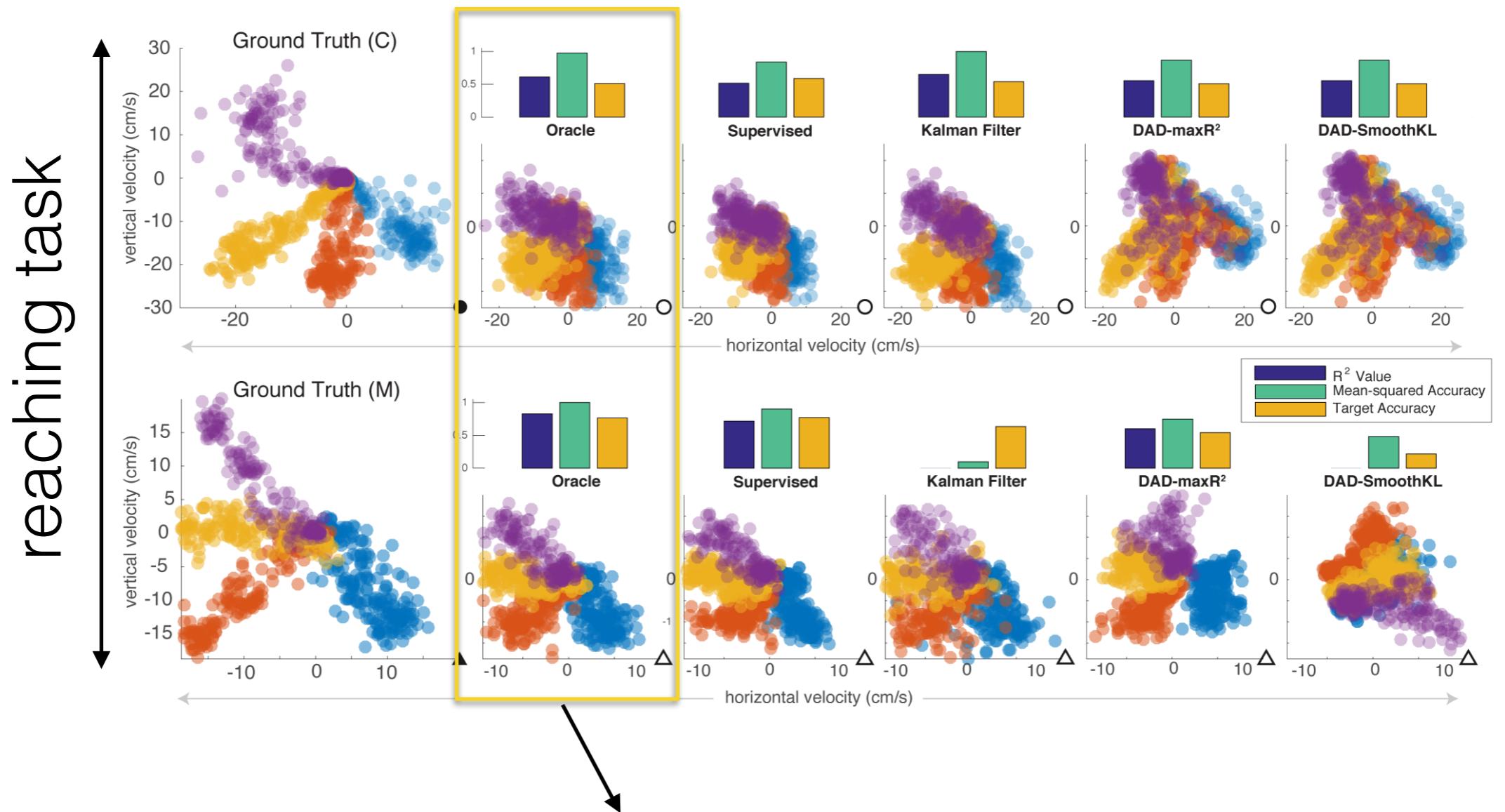
$$\mathbf{H}^* = \arg \min_{\mathbf{H} \in \mathbb{R}^{d \times 3}} \text{KL}(p || q)$$

Estimate \mathbf{p} from $\tilde{\mathbf{V}}$
Estimate \mathbf{q} from $\hat{\mathbf{V}} = \mathbf{H}\mathbf{Y}_p$

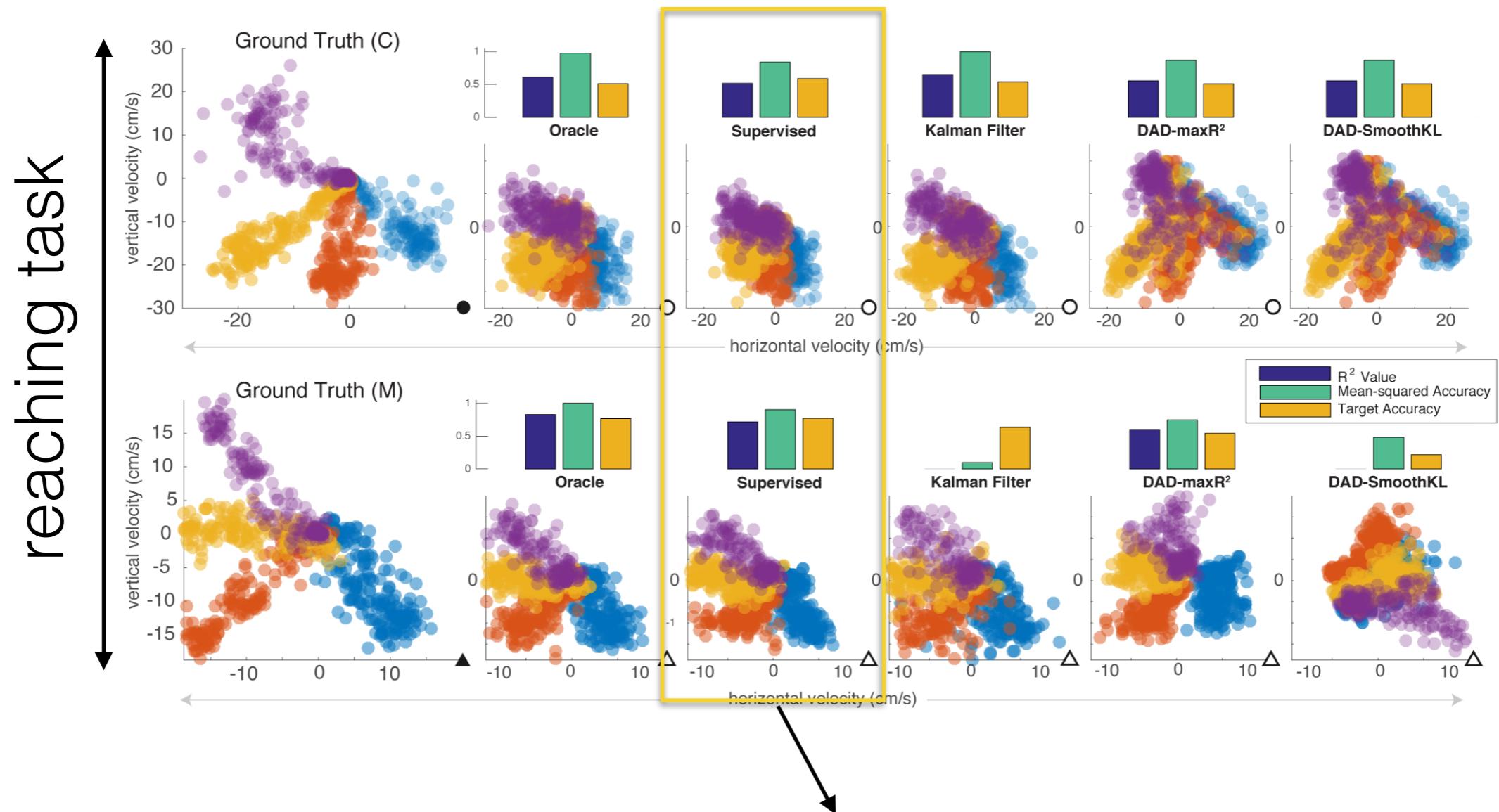
model selection



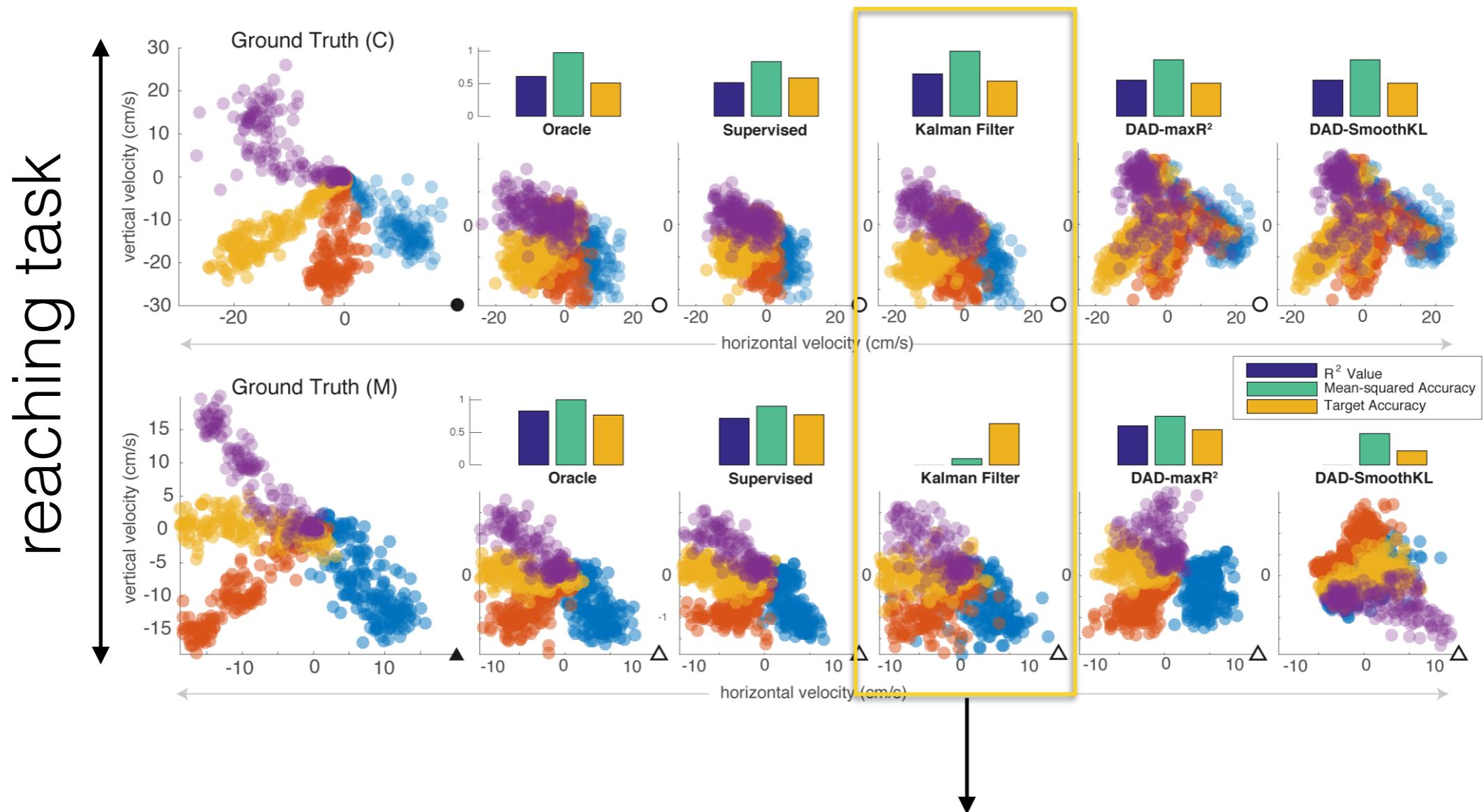
decoding results



decoding results

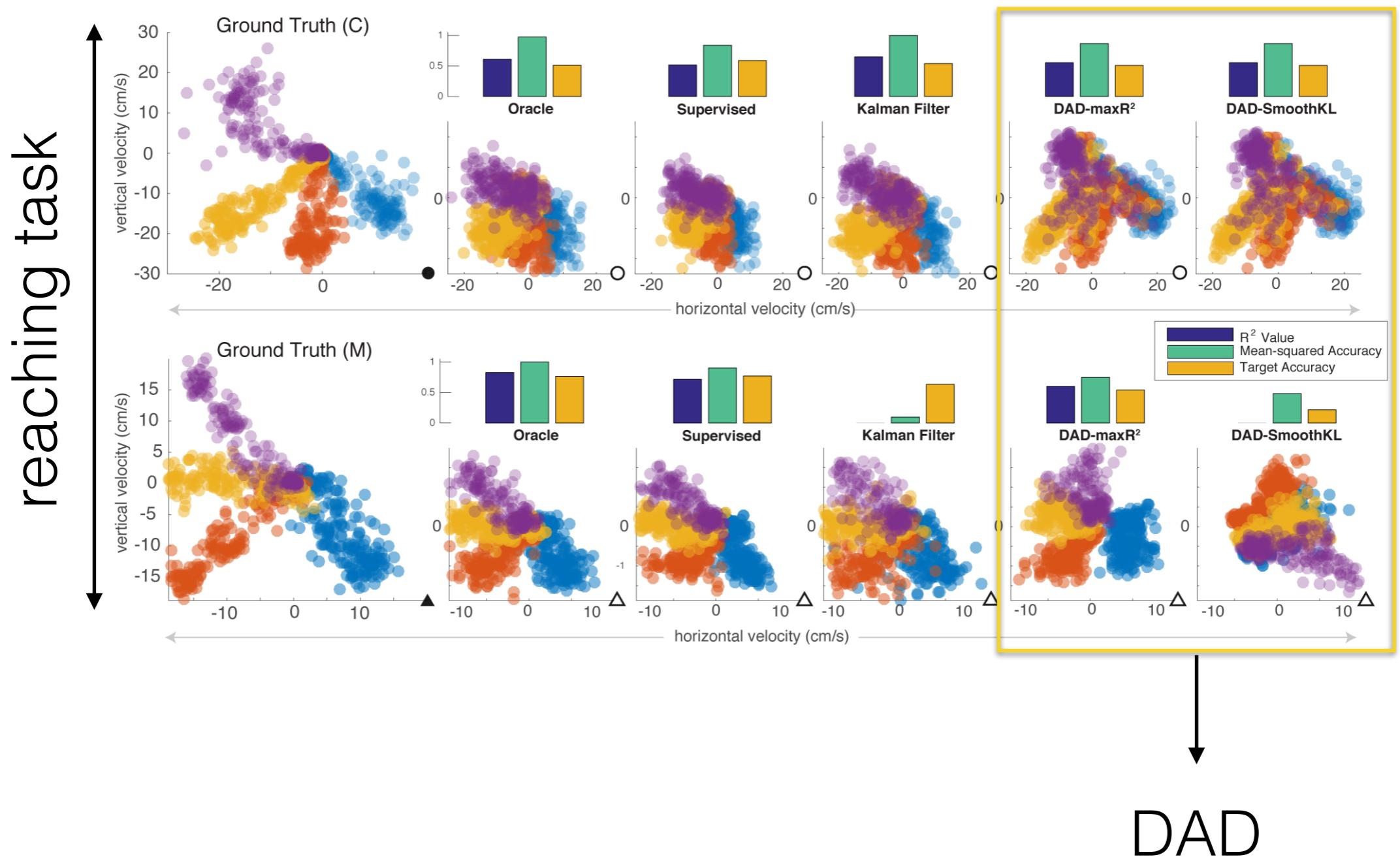


decoding results

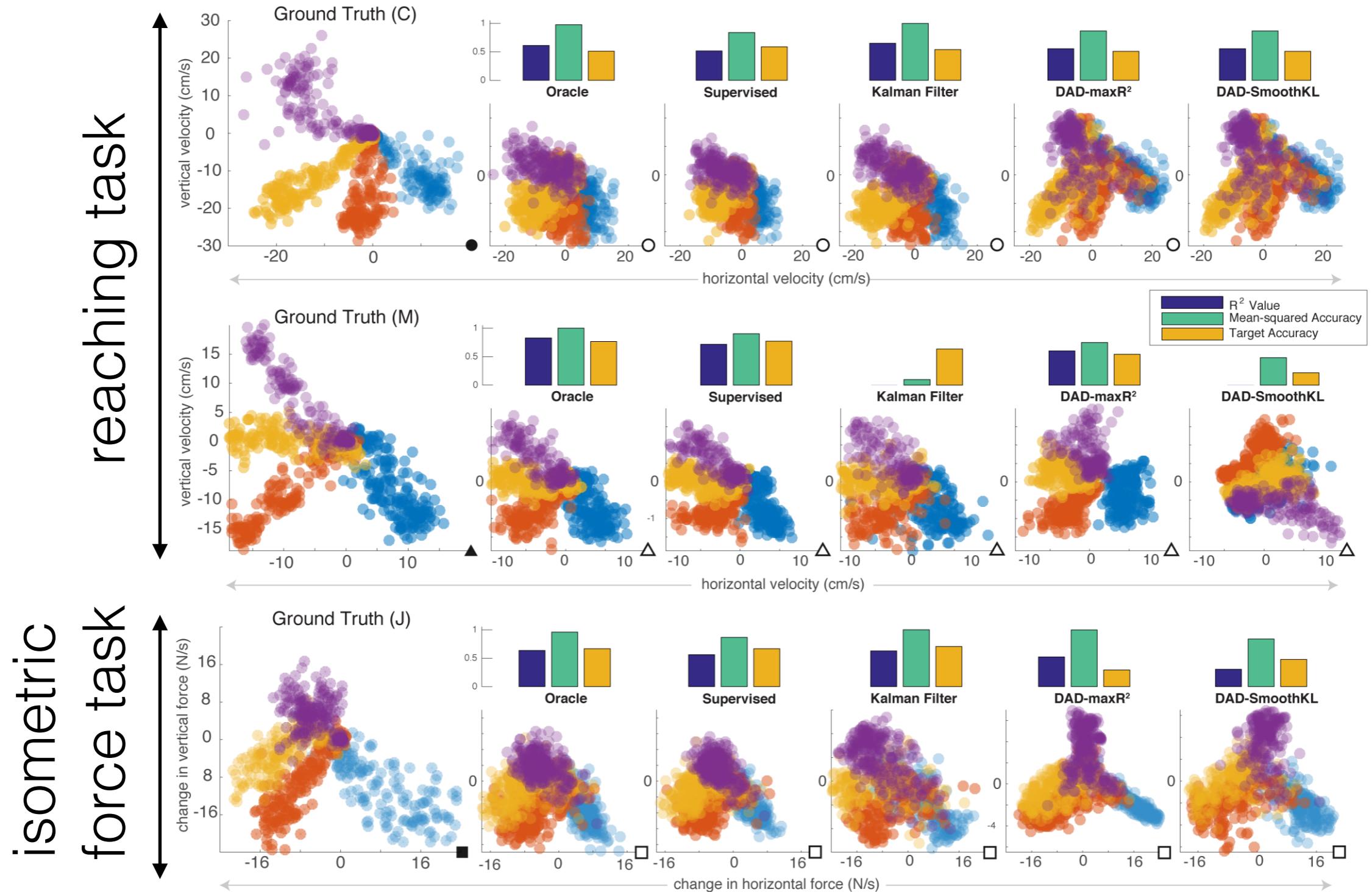


supervised method which
leverages dynamics

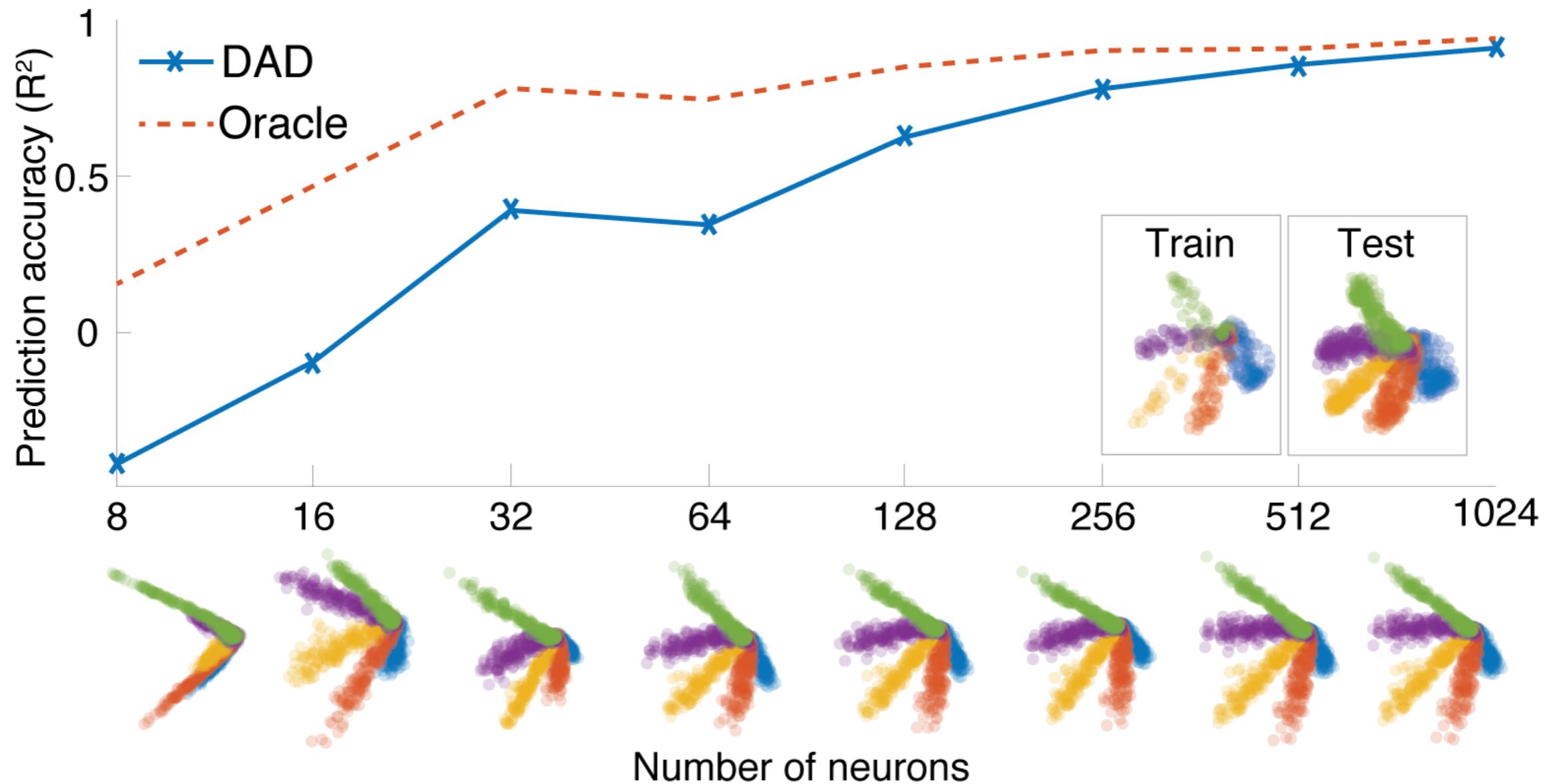
decoding results



decoding results



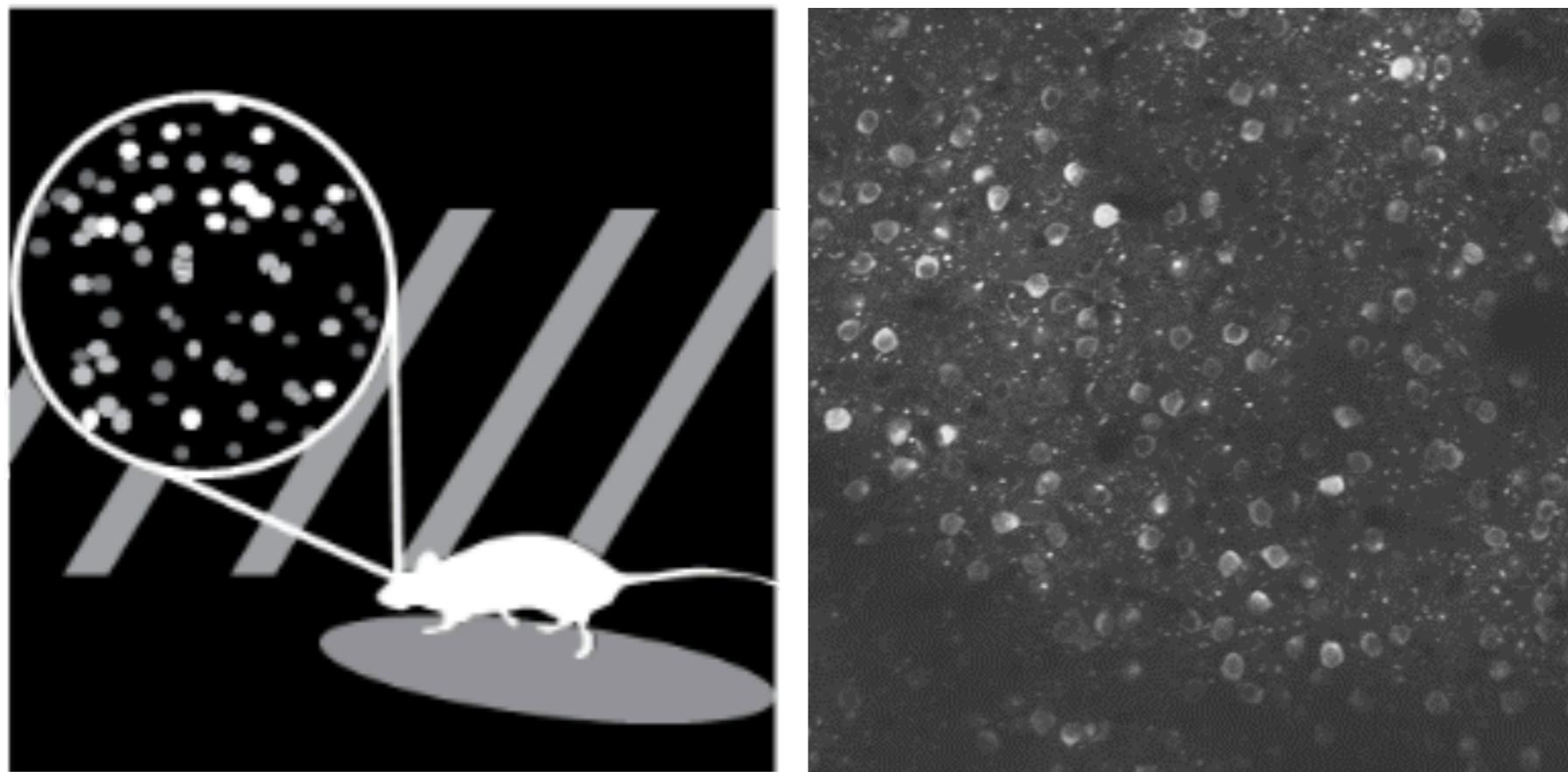
increasing the population size



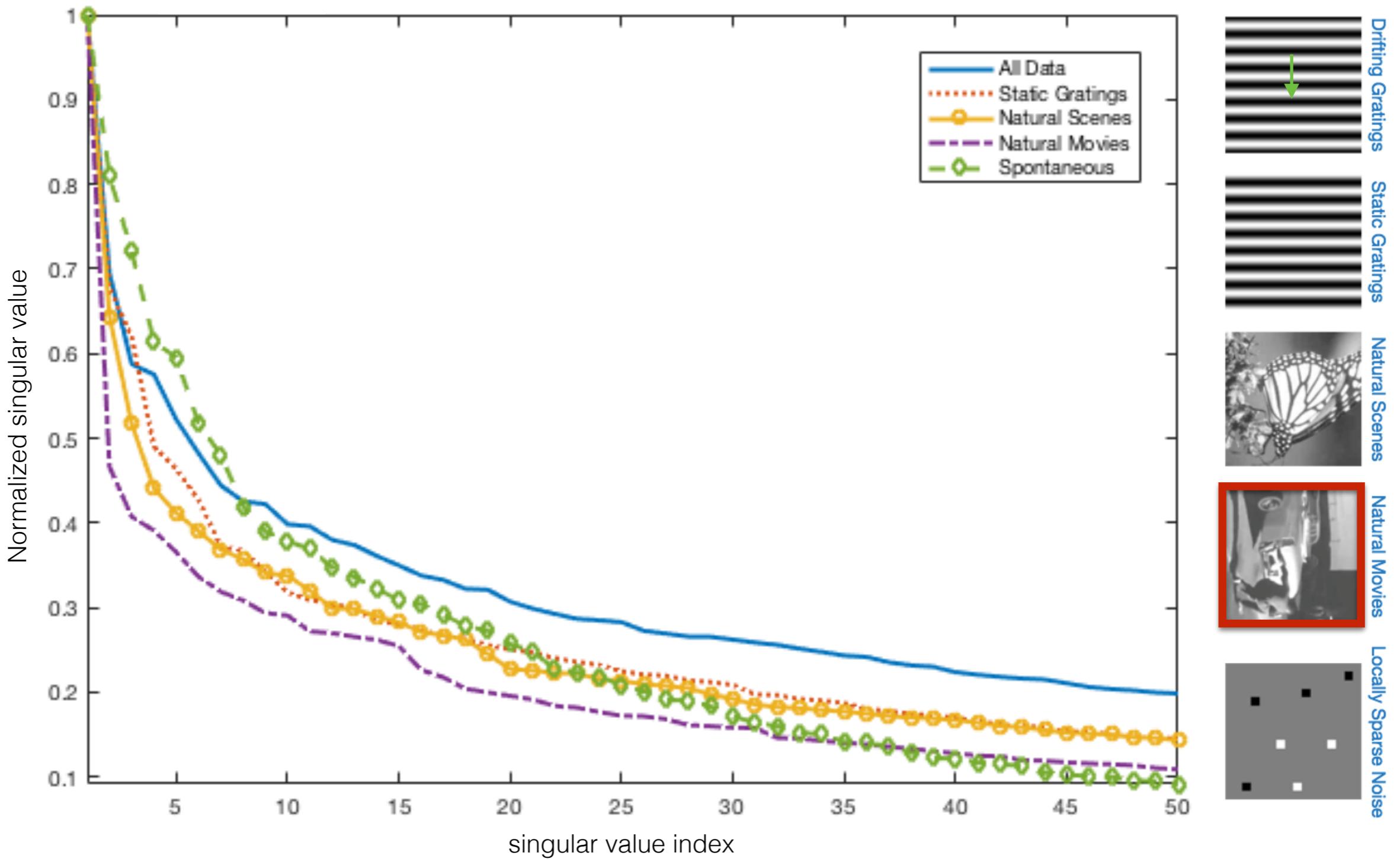
application to
visual coding

visual coding

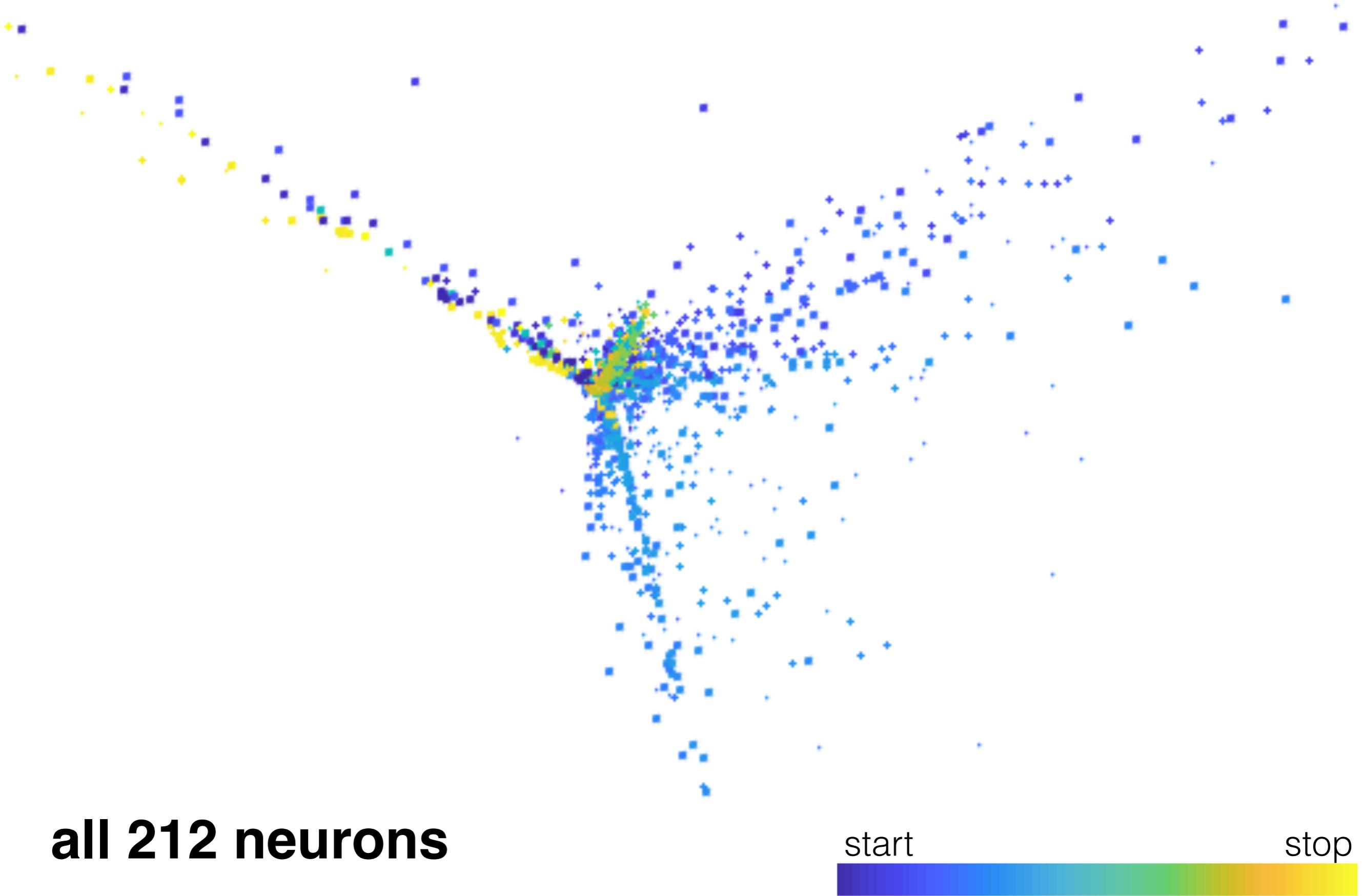
Allen Institute Brain Observatory



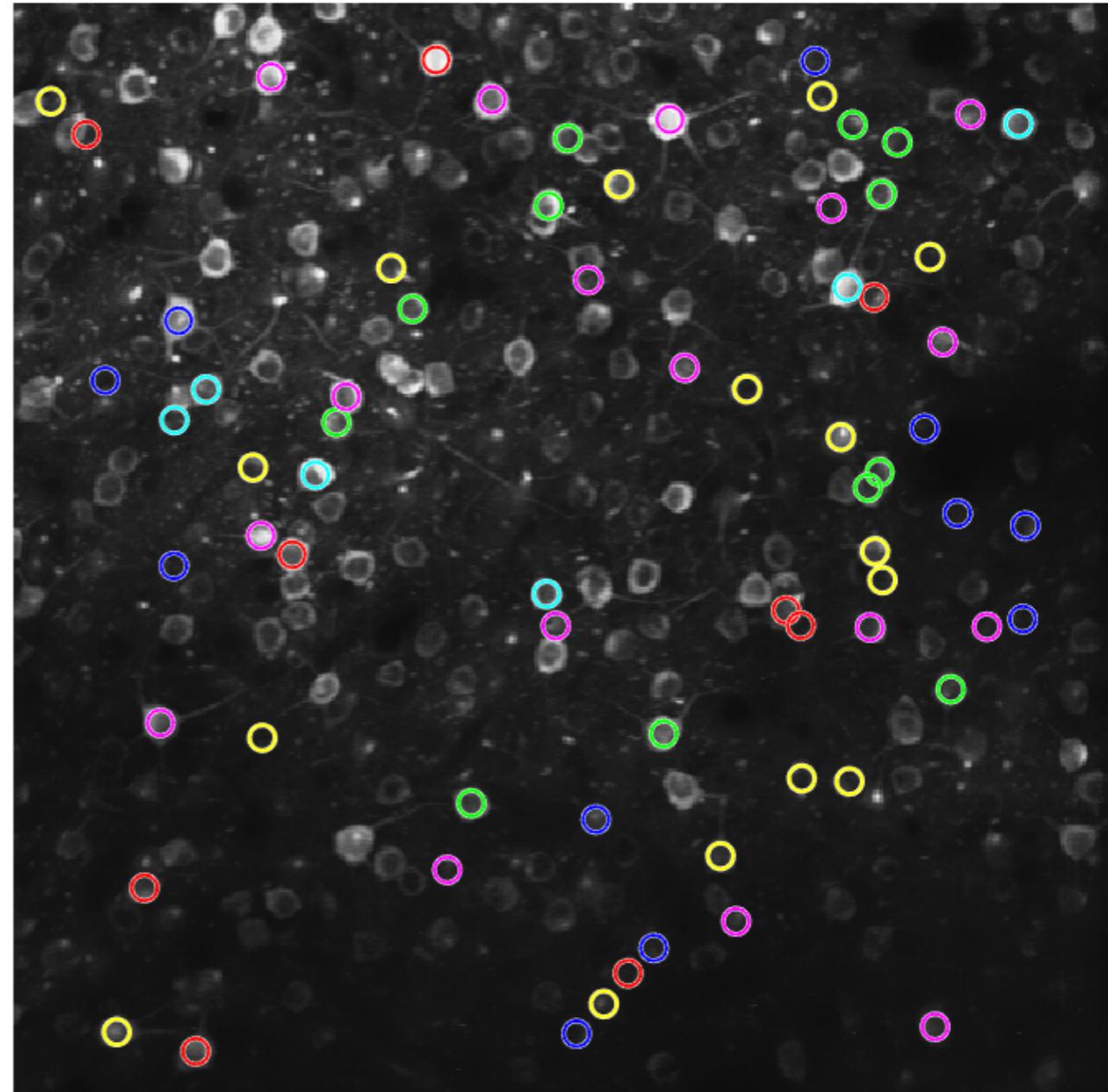
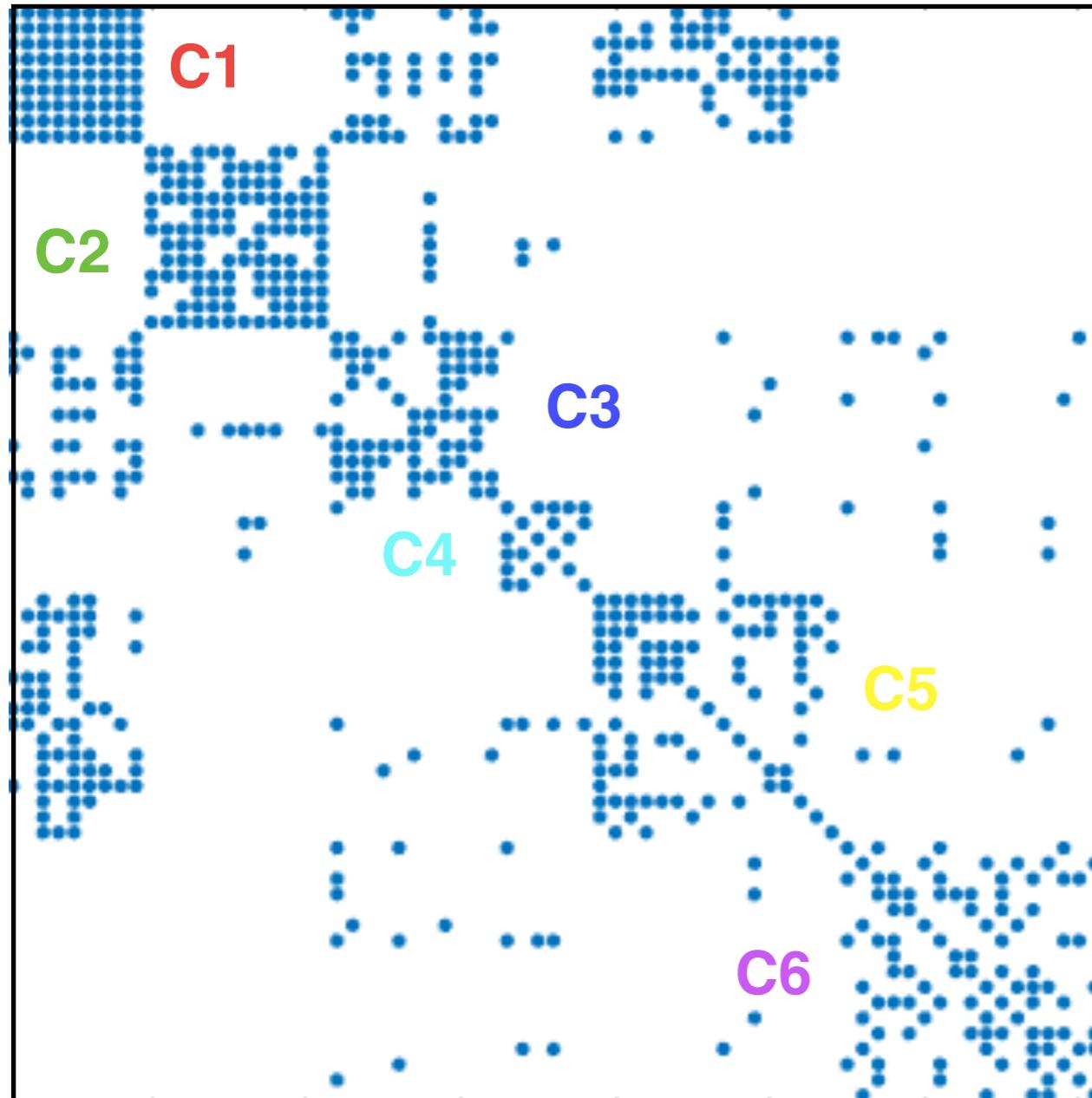
naturalistic stimuli are low-d



visualizing population dynamics

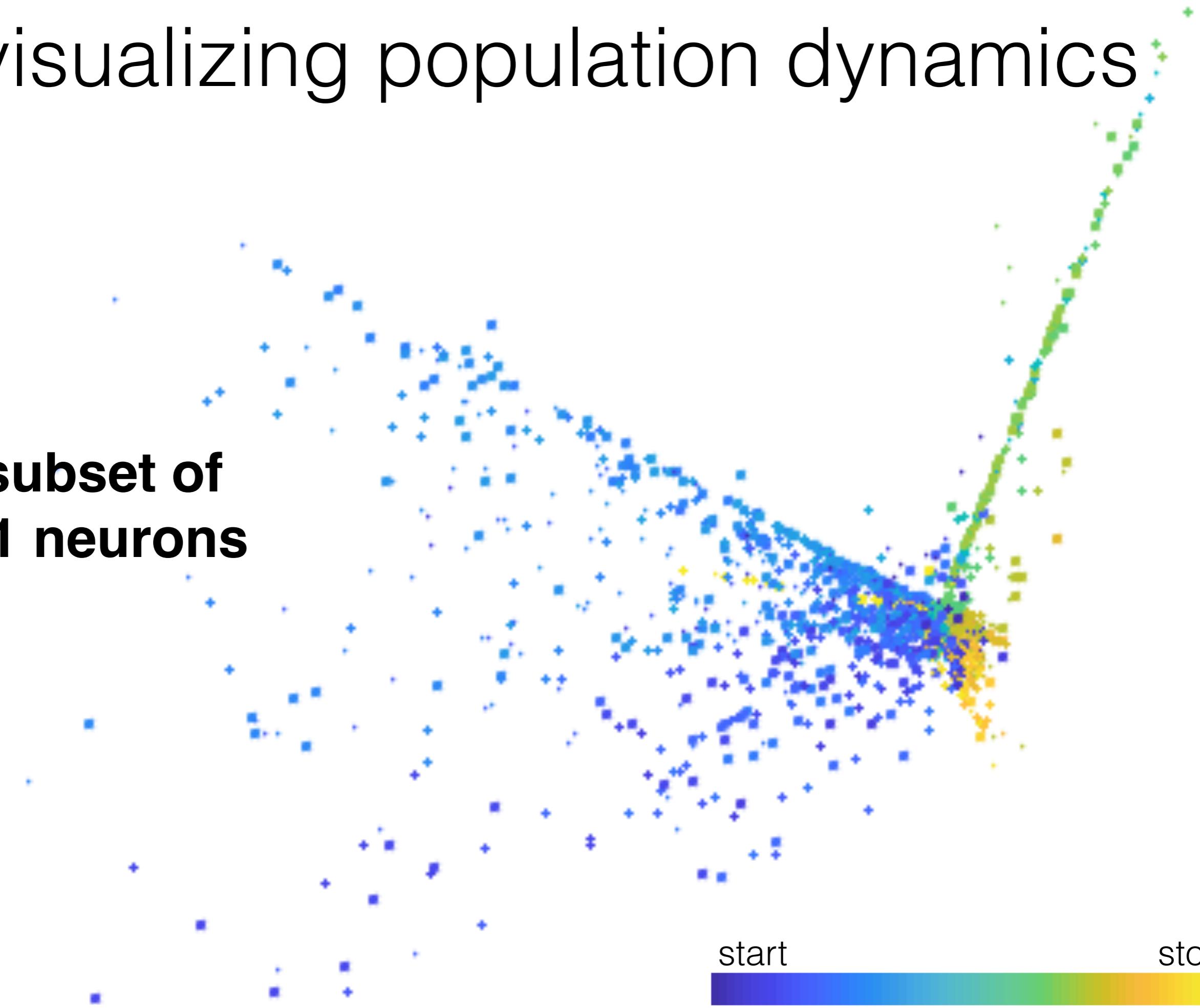


cluster analysis - natural movies

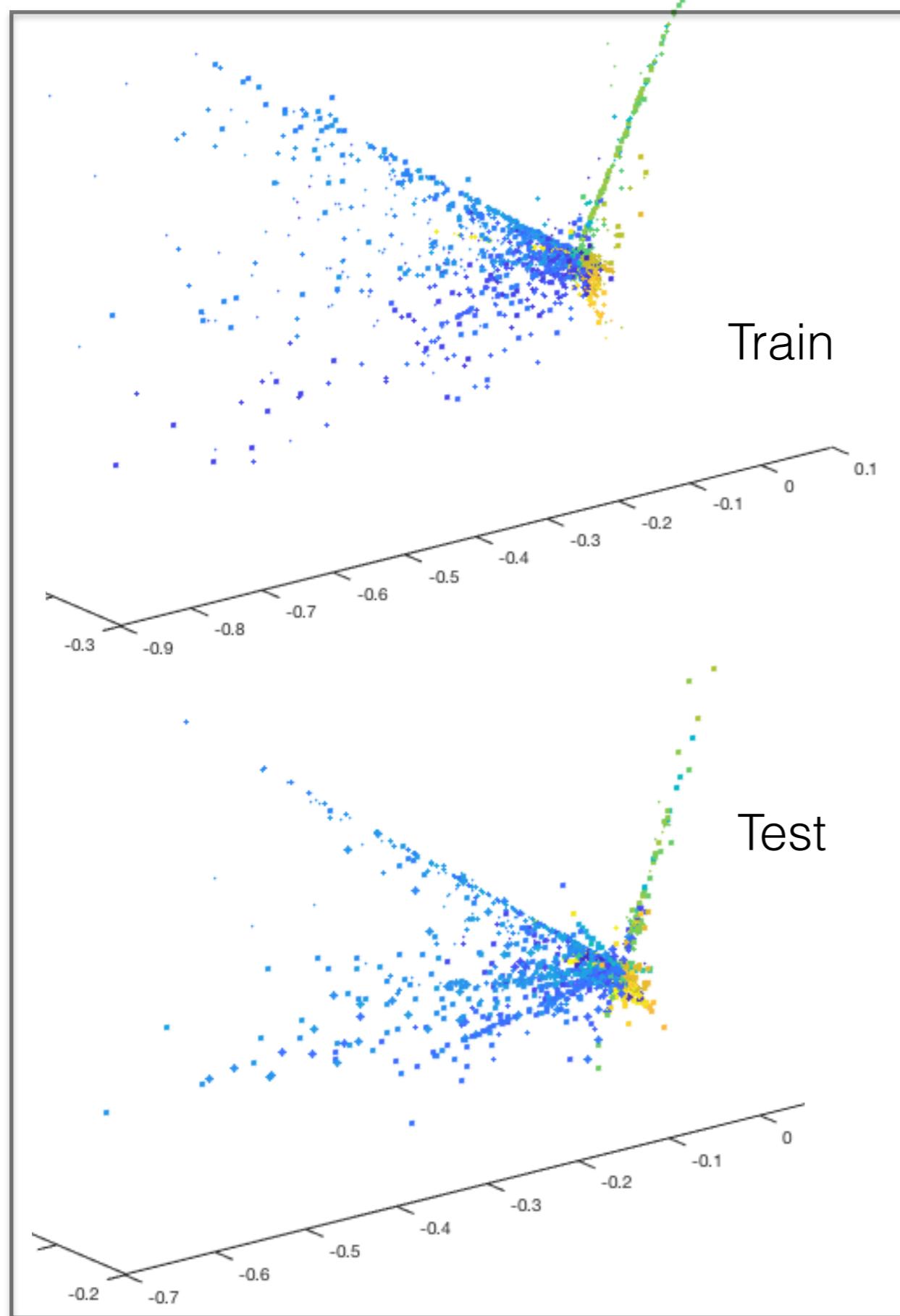


visualizing population dynamics

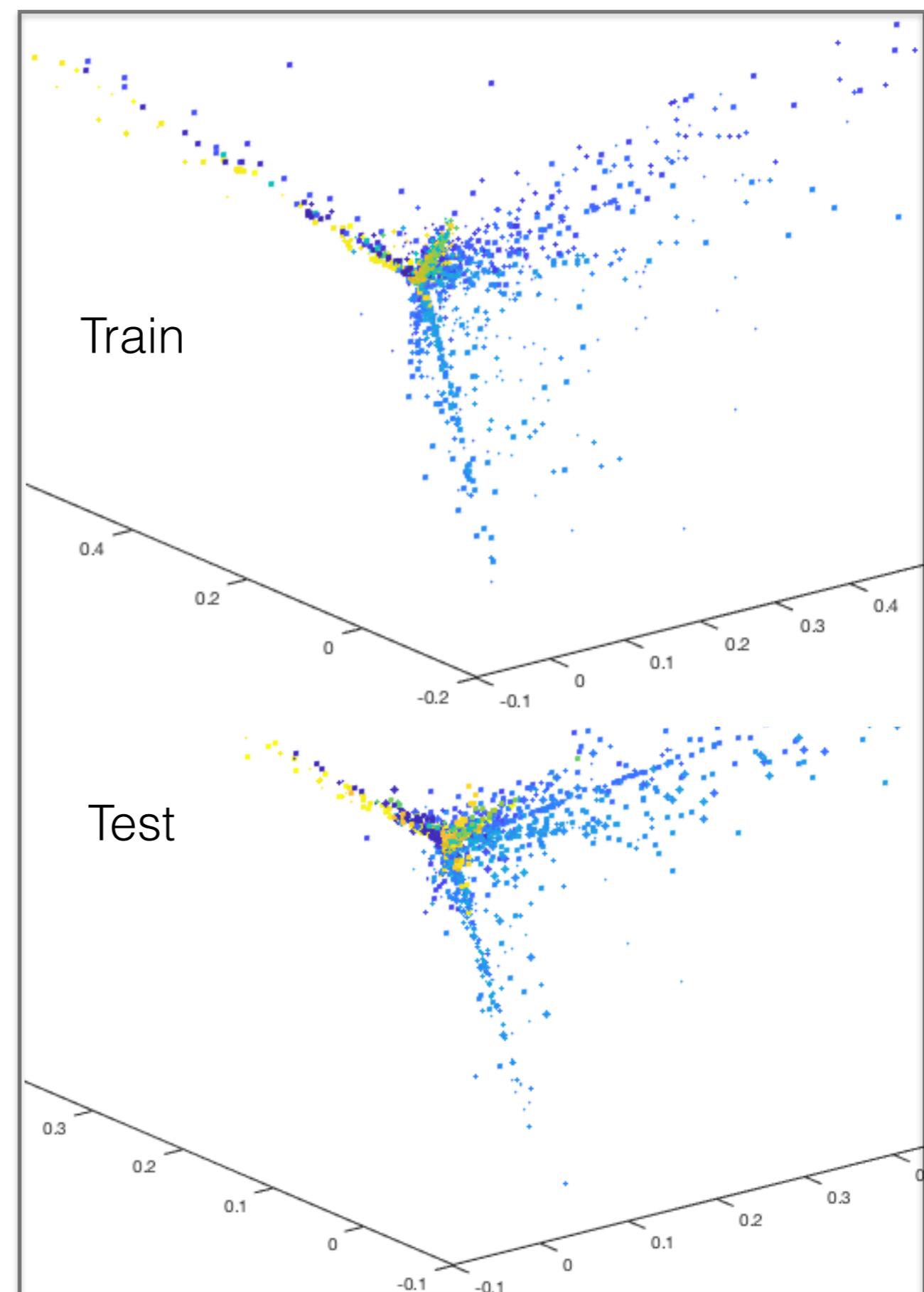
**subset of
71 neurons**



subset



all



summary

overview of low-dimensional models

- Linear subspace models (PCA, FA, NMF)
- Manifold models (Isomap, LLE)
- Clustering models (kmeans)
- Unions of subspaces (SSC)

example 1: movement decoding

- use movement priors to guide factorizations
- decode without supervised data

example 2: visual coding

- cluster neurons then factorize
- not all neurons are created equal

collaborators

movement decoding

Mohammad Gheshlagi Azar (DeepMind)
Konrad Kording (UPenn)
Lee Miller (Northwestern)

visual coding

Saskia de Vries (Allen Institute)

code/data refs

Matlab Toolbox for dimensionality reduction

- <https://lvdmaaten.github.io/drtoolbox/>

Python Tutorials on PCA

- https://sebastianraschka.com/Articles/2015_pca_in_3_steps.html

MATLAB Tutorial on Isomap

- http://www.numerical-tours.com/matlab/shapes_7_isomap/

Distribution Alignment Decoding (DAD)

- <https://github.com/KordingLab/DAD/tree/master/data/demo>

paper refs

Dimensionality reduction for neural data (Review)

- [https://stat.columbia.edu/~cunningham/pdf/
CunninghamNN2014.pdf](https://stat.columbia.edu/~cunningham/pdf/CunninghamNN2014.pdf)

Distribution Alignment Decoding (DAD)

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thank you!

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